Exploiting multiple scattering in CALIPSO measurements to retrieve liquid cloud properties

Nicola Pounder, <u>Robin Hogan</u>, Lee Hawkness-Smith, Andrew Barrett University of Reading, Assimila Ltd., Met Office, ECMWF

The problem with liquid clouds

- 90% of liquid clouds over the oceans; 90% of those contain drizzle
- Lidar signal strongly attenuated & contaminated by multiple scattering



• Can we use the lidar multiple scattering signal to estimate cloud properties (e.g. Polonsky & Davis 2004; Cahalan et al. 2005)?

Liquid cloud properties from space

• High resolution (~1 km) integrated properties (LWP, τ) depend on:



 CALIPSO multiple scattering can potentially fill a gap at night (in the day the solar background is usually too high)

Retrieval ingredients

- Fast forward model for lidar multiple scattering
 - Hogan (2008) for small-angle scattering
 - Hogan and Battaglia (2008) for wide-angle
 - Several milliseconds to compute a profile



- Variational retrieval framework
 - "CAPTIVATE" (Clouds, Aerosol and Precipitation from mulTiple Instruments using a VAriational **TEchnique**)
 - Will generate an official product for EarthCARE



- One-sided gradient constraint
 - Add a term to the cost function to penalize LWC gradients that are steeper than adiabatic

Liquid water content, LWC [g m⁻³]



Multiple-FOV lidar

- Pounder et al. (2012) showed that this approach with three fields of view could retrieve the vertical extinction profile down to around 6 optical depths
- Good constraint on much higher optical depths
- Applied to airborne THOR lidar

Single FOV lidar (e.g. CALIPSO)?



- Simulated clipped triangular profile
 - with gradient constraint

- Triangular profile
 - with gradient constraint

- Triangular profile
 - without gradient constraint
 - Much poorer profile





- Retrieved optical is unbiased up to around 50
- Larger values tend to be underestimated
 - Not many photons get back from this deep in the cloud
- If gradient constraint turned off:
 - Much poorer extinction profile
 - But retrieved optical depth only slightly poorer

Application to real CALIPSO data

CALIPSO attenuated backscatter observations:



• At final iteration of retrieval, forward-modelled backscatter looks like:





Comparison to CloudSat-estimated LWP



- Hawkness-Smith (PhD, 2010) derived LWP from CloudSat pathintegrated attenuation over oceans
 - Similar to Lebsock et al. (2011)
 - Unbiased agreement with CALIPSO multiple scattering retrieval for assumed number concentration
 - Some scatter!

A simpler approach?

- Optical depth can be estimated simply from integrated backscatter B!
 - Some dependence on the shape of the extinction profile



 Ground-based lidar: weak wide-angle multiple scattering leads to constant B with optical depth so can use for calibration (O'Connor et al. 2004)

Summary and outlook

- Via a fast multiple scattering model, we can interpret CALIPSO backscatter at night to retrieve optical depth and to some extent the vertical profile of extinction
- This capability is part of "unified" CAPTIVATE retrieval scheme that will be applied to A-Train and EarthCARE data
- Will be more difficult with EarthCARE due to narrower field of view

- Recently developed a fast forward model for lidar *depolarization* due to multiple scattering, which could provide an additional constraint
- The extinction coefficient profile would be retrieved much better from a future spaceborne lidar with *multiple fields of view*!