

Introduction

Satellite cloud property retrievals are used for both initialization and validation of cloud models and global circulation models. It is therefore important to characterize the uncertainty of satellite retrievals and identify any existing biases. The NASA Langley Cloud and Radiation Group uses a common set of algorithms to retrieve cloud thermodynamic phase, altitude, optical depth, and water path from imagers such as the Advanced Very High Resolution Radiometer (AVHRR), and the Clouds and the Earth's Radiant Energy System (CERES) Clouds Working Group routinely retrieves these same properties from Moderate-Resolution Imaging Spectroradiometer (MODIS) and Visible-Infrared Imaging Radiometer Suite (VIIRS) data. Active remote sensors in the A-Train Constellation such as the Cloud-Aerosol Lidar with Orthogonal Polarization (CALIOP) provide a wealth of information to independently assess the passive satellite retrievals.

Data and Validation Strategy

Satellite imager data:

- NOAA-18 AVHRR 4-km Global Area Coverage (GAC) data (Oct 2008)
- Aqua-MODIS CERES Clouds Edition 4; subsampled 1-km pixels; 15 days from Oct 2008, Jul 2012, Oct 2012, Apr 2013
- SNPP-VIIRS, CERES Clouds Edition 1; subsampled 750-m pixels; 5 days from March 2013

Products used to validate imager retrievals:

- CALIPSO Vertical Feature Mask (VFM)
- CALIPSO 5-km Cloud Layers Product (05kmCLay)
- CALIPSO 333-m Cloud Layers Product (333mCLay)
- AMSR-E Level 2 Ocean Product (Wentz Algorithm)

Spatial/temporal matching:

CALIPSO provides cloud heights on various spatial scales ranging from 333 m to 80 km. Many of the CALIPSO products are provided at 5-km resolution which is comparable to the spatial resolution of most imagers. For this reason, all satellite data is matched spatially to 5-km segments of the CALIPSO ground track. Imager pixels within 2.5 km of each segment's midpoint and within 15 minutes of the CALIPSO scan time are considered matches. Since AMSR-E has a larger footprint, the mean LWP is computed for all imager pixels within the AMSR-E footprint nearest the CALIPSO footprint. While MODIS and VIIRS view the CALIPSO ground track near nadir, AVHRR may have off-nadir views. All AVHRR pixels were corrected for parallax. In the following sections, all differences are computed as AVHRR/MODIS/VIIRS minus CALIOP/AMSR-E.

INSTRUMENT/PRODUCT	APPROX. SPATIAL RES.	CLOUD PROPERTIES PROVIDED
VFM	1/3 - 80 km	cloud mask (see Q. Trepte poster, P6-354) phase
05kmCLay	5 km	optical depth (COD), ice water path (IWP)
333mCLay	1/3 km	cloud top altitude (CTA)
AMSR-E	12 km	liquid water path (LWP)

Cloud Phase

CALIPSO VFM data were used to identify overcast scenes consisting of single-phase clouds, i.e. 100% water or 100% ice. Scenes containing faint cirrus detected by CALIOP using 80-km horizontal averaging were excluded from the analysis. The fraction of correctly identified scenes (FC) is shown in the chart below for all three imagers and for different surface types.

DAYTIME	FRACTION OF SCENES WITH CORRECTLY IDENTIFIED PHASE		
	AVHRR	MODIS	VIIRS
Nonpolar, Ocean	0.956	0.978	0.991
Nonpolar, Land	0.913	0.936	0.955
Polar, Ocean	0.922	0.959	0.971
Polar, Land	0.869	0.943	0.978
Global, Snow/Ice	0.809	0.926	0.821
NIGHTTIME			
Nonpolar, Ocean	0.927	0.947	0.976
Nonpolar, Land	0.906	0.914	1.000*
Polar, Ocean	0.823	0.912	0.945*
Polar, Land	0.938	0.915	no data
Global, Snow/Ice	0.873	0.876	0.814

* computed with fewer than 100 data points

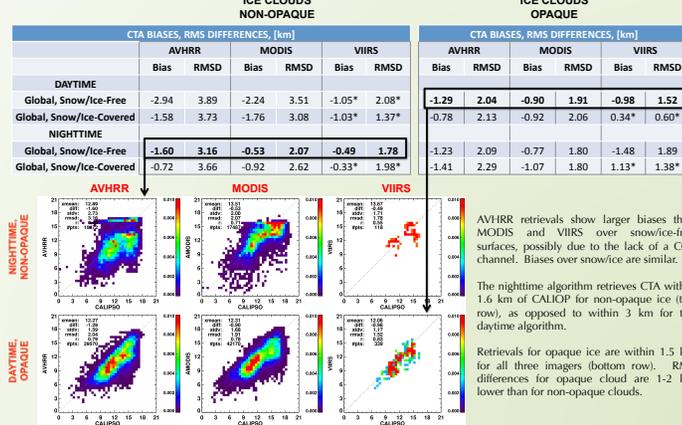
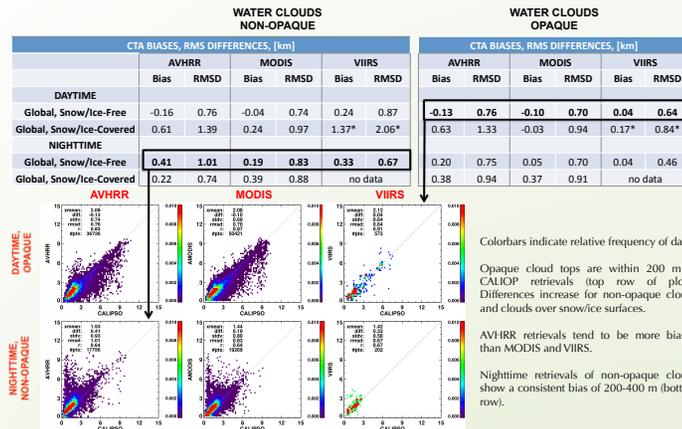
The correct phase is identified by all three imagers over 90% of the time in most cases.

AVHRR FC values are typically within 2-3% of the MODIS and VIIRS values.

There is a bias towards ice clouds for "twilight" conditions, i.e., 82° < solar zenith angle < 90° (not shown).

Cloud Altitude

Cloud top altitude (CTA) differences (km, imager minus CALIOP) were computed as a function of thermodynamic phase (water/ice), solar zenith angle (day/night), surface type (snow/ice-free, snow/ice-covered), and cloud opacity (non-opaque, opaque). Root-mean-square differences (RMSD) were also computed and are given in the tables below.



Summary

Cloud property retrievals from imagers such as AVHRR, Aqua-MODIS, and VIIRS are being validated with A-Train sensors such as CALIOP and AMSR-E.

Water cloud top altitudes are retrieved to within 400 m of CALIOP values. Opaque ice cloud tops are retrieved to within 1 km. CTA biases are generally smaller for opaque than non-opaque clouds.

Nighttime optical depths and IWP compare well with CALIOP. Increased surface reflection causes overestimates over snow/ice surfaces during the day. IR-only techniques can help reduce daytime biases.

Daytime LWP retrievals for non-precipitating clouds are biased by less than 6 g m⁻² compared to AMSR-E microwave retrievals and show moderate to high correlation.

AVHRR retrievals are nearly as accurate as MODIS and VIIRS retrievals in many cases.

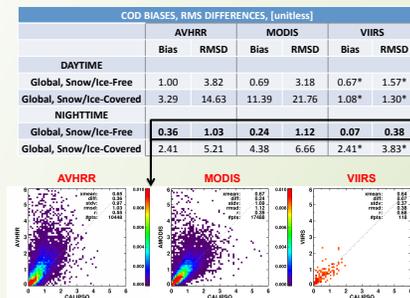
Validation for VIIRS will be ongoing as the record becomes more extensive.

Cloud Optical Depth

Cloud optical depth (COD) comparisons are limited to non-opaque ice-phase clouds, corresponding to COD < -6, because they do not completely attenuate the lidar beam.

The smallest differences occur for nighttime snow/ice-free conditions when IR-only algorithms are used to retrieve COD.

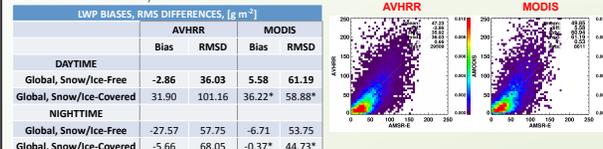
Differences are largest for daytime snow/ice surfaces because of increased reflection from bright surfaces. See S. Bedka poster (P6-344) for techniques being used to mitigate these difficulties.



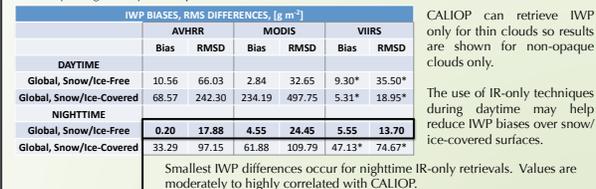
Cloud Water Path

The AMSR-E liquid water path (LWP) retrieval algorithm is performed over water surfaces only, so no comparisons with AMSR-E over land are currently available. Ground-based microwave radiometer (MWR) observations can be used for validation in limited locations. Precipitating clouds were excluded from the analysis, effectively limiting comparisons to clouds with LWP < 200 g m⁻², and no distinction was made for opaque and non-opaque clouds.

The AMSR-E and VIIRS data records have no temporal overlap, so LWP comparisons are shown for AVHRR and MODIS only.



LWP is overestimated over snow/ice-covered surfaces during the day because of surface reflection. Nighttime LWP is underestimated because optical depths greater than 4-6 cannot be retrieved with any certainty using IR-only techniques.



Smallest IWP differences occur for nighttime IR-only retrievals. Values are moderately to highly correlated with CALIOP.

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