Development and Evaluation of New Monin-Obukhov and Bulk Richardson Parameterizations to Improve the Representation of Surface-Atmosphere Exchange in Weather Forecasting Models

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### **Monin-Obukhov Parameterizations**

Gradients of temperature, moisture and wind can be written as functions of  $\frac{z}{L}$ , assuming a horizontally-homogenous near-surface flux layer:

$$L = -\frac{\overline{\theta_{\nu}}u_*^3}{\kappa g \overline{w' \theta_{\nu 0}'}}$$



$$\frac{\partial \overline{\Theta}}{\partial z} \frac{u_* \kappa z}{H} = \phi_h(\frac{z}{L})$$

 $\frac{\partial \overline{q}}{\partial z} \frac{u_* \kappa z}{LE} = \phi_q(\frac{z}{L})$ 

$$\phi_h = \alpha_h (1 - \beta_h \frac{z}{L})^{-\frac{1}{2}}$$

$$\phi_q = \alpha_q (1 - \beta_q \frac{z}{L})^{-\frac{1}{2}}$$

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# Land Atmosphere Feedback Expt.



Array of sfc. instruments and PBL profilers to study interactions between the land-surface and atmosphere

# **ATDD Tower Measurements**

#### 2 m Tripod

Instrument	Sampling Height(s) (m AGL)
Propeller anemometer	2
Closed path gas analyzer	2
Sonic anemometer	2
10 m Tower	
Instrument	Sampling Height(s) (m AGL)
HMP110 T, RH probe	2
Aspirated PRT	2 ,10
Pressure sensor	1
Hukseflux net radiometer	2.5
TP01 soil temperature probe	-0.05, -0.10, -0.20
Decagon soil moisture probe	-0.05, -0.10, -0.20
Propeller anemometer	2, 10
PAR sensor	2.5
Closed path gas analyzer	10
Sonic anemometer	10
Other	
Instrument	Sampling Height(s) (m AGL)
Rain gauge	2.5

![](_page_3_Picture_3.jpeg)

# **Site Characteristics**

![](_page_4_Figure_1.jpeg)

# **Monin-Obukhov Parameterizations**

![](_page_5_Figure_1.jpeg)

LAFE datasets show significant departure from classical relationships developed in the literature

## **Bulk Richardson Parameterizations**

$$Ri = \frac{g \frac{\partial \overline{\theta_{v}}}{\partial z}}{\overline{\theta_{v}} \left[ \left( \frac{\partial \overline{u}}{\partial z} \right)^{2} + \left( \frac{\partial \overline{v}}{\partial z} \right)^{2} \right]}$$

#### From Deardorff (1972):

$$C_u = \frac{u_*}{U_{10}}$$

$$C_t = \frac{\theta_*}{(\theta_v - \theta_{vs})}$$

$$C_r = \frac{(-\overline{w'q'})_s}{u_*(q-q_s)}$$

$$C_u = \alpha_u (1 - \beta_u R i_b)^{\frac{1}{3}}$$

$$C_t = \alpha_t (1 - \beta_t R i_b)^{\frac{1}{3}}$$

$$C_r = \alpha_r (1 - \beta_r R i_b)^{\frac{1}{3}}$$

# **Bulk Richardson Parameterizations**

![](_page_7_Figure_1.jpeg)

## **Evaluation Study Area**

![](_page_8_Figure_1.jpeg)

Evaluating MOST Functions  

$$\begin{aligned}
& U_{10} = \frac{u_*}{\kappa} \left[ \ln\left(\frac{z-d}{z_0}\right) - \psi_m\left(\frac{z-d}{L}\right) + \psi_m\left(\frac{z_0}{L}\right) \right] \\
& \Delta \theta = \frac{\theta_*}{\kappa} \left[ \ln\left(\frac{z_2-d}{z_1-d}\right) - \psi_h\left(\frac{z}{L}\right)_2 + \psi_h\left(\frac{z}{L}\right)_1 \right] \\
& \Delta q = \frac{q_*}{\kappa} \left[ \ln\left(\frac{z_2-d}{z_1-d}\right) - \psi_q\left(\frac{z}{L}\right)_2 + \psi_q\left(\frac{z}{L}\right)_1 \right] \\
& \text{Where,} \\
& = 2\ln\left(\frac{1+\phi_m^{-1}}{2}\right) + \ln\left(\frac{1+\phi_m^{-2}}{2}\right) \\
& - 2\tan^{-1}\phi_m^{-1} + \frac{\pi}{2} \\
& \psi_h = 2\ln\left(\frac{1+\phi_h^{-2}}{2}\right) \\
& \psi_q = 2\ln\left(\frac{1+\phi_q^{-2}}{2}\right) \\
& \psi_q = 2\ln\left(\frac{1+\phi_q^{-2}}{2}\right)
\end{aligned}$$

 $\psi_m$ 

# Evaluating Rib Functions

$$C_u = \frac{u_*}{U_{10}}$$

$$U_{10} = \frac{u_*}{C_u}$$

$$C_t = \frac{\theta_*}{(\theta_v - \theta_{vs})}$$

$$\Delta \theta = \frac{\theta_*}{C_t}$$

$$C_r = \frac{(-\overline{w'q'})_s}{u_*(q-q_s)}$$

$$\Delta q = \frac{q_*}{C_r}$$

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## $U_{10}$

![](_page_11_Figure_1.jpeg)

#### $\Delta \theta$

![](_page_12_Figure_1.jpeg)

![](_page_13_Picture_0.jpeg)

![](_page_13_Figure_1.jpeg)

#### $Ri_b$ Fits for Unstable and Stable Conditions For $Ri_b > 0$ $C_{u,t,r} = \alpha_{u,t,r} \ln(Ri_b) + \beta_{u,t,r}$

![](_page_14_Figure_1.jpeg)

#### $U_{10}, \Delta\theta, \Delta q \text{ for } -5 < Ri_b < 5$

![](_page_15_Figure_1.jpeg)

#### Summary and Outlook

![](_page_16_Figure_1.jpeg)