Anemometer Calibration Requirements for Wind Energy Applications





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Outline

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- Wind Sensors Used in Wind Power
- Basic Anemometer Calibration
- Applicable Test Standards
- Test Facility Requirements
- Facility Performance Evaluation
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- Summary



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Importance of Wind Sensors in Wind Energy

- Wind Plant Operations
 - Validate wind turbine power output
 - Control start-up and shut-down
- Wind Turbine Performance Evaluations
 - Power curve (wind turbine power output as a function of wind speed)

> Wind Energy Site Assessments

• Use power curves and wind distributions to estimate annual energy production for power purchase agreements





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Sample Turbine Power Curve

- 1.5 MW rated power reached at ~12 m/s
- Power estimated at lower wind speeds can be as much as 30% error depending on curve



Wind Sensors Used in Wind Power

Cup Anemometers





Anemometers



- Wind turbines are designed to generate power from direct incoming flow
- Key measure from a wind sensor is the magnitude of the horizontal wind speed component



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Basic Anemometer Calibration

Anemometer Output \Leftrightarrow Controlled Reference Speed



Rotation rate (i.e., Hz or rpm)

> **Analog voltage** or conditioned digital signal

Wind generated from a controlled wind tunnel







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Perform a Least Squares Fit ⇒ Linear Transfer Function



Applicable Test Standards

- ASTM D5096-02, "Standard test method for determining the performance of a cup anemometer or propeller anemometer"
- ASTM D6011-96, "Standard test method for determining the performance of a sonic anemometer/thermometer"
- ISO 17713-1, "Meteorology Wind measurements Part 1: Wind tunnel test methods for rotating anemometer performance"
- ISO 16622, "Meteorology Sonic anemometers/thermometers Acceptance test methods for mean wind measurements"
- IEC 61400-12-1, "Wind turbines Part 12-1: Power performance measurements of electricity producing wind turbines"
- IEC 61400-12-2, "Wind turbines Part 12-2: Power performance of electricity producing wind turbines using nacelle anemometry"

General requirement is to perform anemometer calibrations in a *uniform-flow, low-turbulence wind tunnel*





Test Facility Requirements

Wind Tunnel Characteristic	Standards Requirements
Speed Range	IEC 61400-12-1 (4-16 m/s); Others based on % of application speed
Flow Uniformity	IEC 61400-12-1 (<0.2%); Others (<1%)
Wind Gradient	IEC 61400-12-1 (<0.2%)
Turbulence Intensity	IEC 61400-12-1 (<2%); Others (<1%)
Density Uniformity	ASTM D5096-2, ISO 17713-1 (<3%)
Data Acquisition	Resolution 0.02 m/s, minimum sampling 10 Hz, duration 30-100 sec
Model Blockage	10% max for open test sections, 5% max for closed test sections
Repeatability	IEC 61400-12-1 (<0.5% at 10 m/s test speed)
Interlaboratory Comparison	IEC 61400-12-1 (within 1% in 4-16 m/s test speed range)





Test Facility Requirements

Common Wind Tunnel Configurations





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AIAA R-093-2003, "Calibration of Subsonic and Transonic Wind Tunnels"

General concept is to define dynamic pressure in test section according to the pressure drop generated by the wind tunnel contraction section.





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Reference speed measurement: *Pitot-static tube system* (as defined by IEC 61400-12-1)

Four Pitot tubes with sensing tips positioned at test section inlet where total and reference ports connected to an MKS 120AD transducer.



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Pitot-Static Tube System General Velocity Equation



$$V = \sqrt{\frac{2\Delta\rho}{\rho}} \xrightarrow{\text{Differential pressure}}_{\text{from Pitot-static tube}}$$

Density of humid air

$$\rho = \frac{1}{R * T} \left[PM_{air} - 2.05 \times 10^{-7} \phi e^{0.0631846T} \left(M_{air} - M_{w} \right) \right]$$

Relative humidity
Ambient pressure

Ambient temperature



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Velocity profiles at center of test section from traversed Pitot tube.







- 1) Profiles mean speed settings from 4 to 26 m/s showed an average test section uniformity within +/-0.2%.
- 2) Preliminary indication of less than 0.2% turbulence.
- 3) Difference in wind speed between center of test section to reference Pitot-static tubes at inlet averages to +0.014%.



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Blockage
Ratio

$$\frac{A_{C3}}{A_{TS}} \le 2\%$$
Empirical
Blockage
Correction

$$k_b = 1 + \frac{1}{4} \frac{A_{C3}}{A_{TS}} = 1.005$$

Test performance requirements according to IEC 61400-12-1

- > Calibration test speeds: 4 to 16 m/s at 1 m/s increments
- > Repeatability (<0.5% at 10 m/s) \Rightarrow within 0.2% for 5 repeated tests
- ➢ Interlaboratory Comparison (+/-1% at 4-16 m/s) ⇒ 1% average variation in comparison to an accredited wind tunnel laboratory in Denmark



0.4

Time

0.6

0.8



Anemometer calibration uncertainty consists of the propagation of errors from three general areas

$$U_{cal} = \sqrt{(U_V)^2 + (U_{IUT})^2 + (U_{LR})^2}$$

Reference wind speed

Test sensor output







Uncertainty in each area includes systematic or Type B errors (*B_i*) and random or Type A errors (*S_i*)

$$U_i = \sqrt{B_i^2 + (tS_i)^2}$$

Coverage factor at 95% confidence



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Uncertainty in reference wind speed

$$J_{V} = \sqrt{B_{V}^2 + (tS_{V})^2}$$

Analyzed from Pitot-static tube velocity equation

$$V = \sqrt{\frac{2\Delta p}{\rho}} \qquad V = C_h k_b k_c \sqrt{\frac{2\Delta p}{\rho}}$$

$$\rho = \frac{1}{R^* T} \left[P M_{air} - 2.05 \times 10^{-7} \phi e^{0.0631846T} (M_{air} - M_w) \right]$$

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$$V=f(M_{air}, M_w, k_b, k_c, C_h, R^*, P, T_K, \Delta p, \phi)$$



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Uncertainty in reference wind speed

$$U_V = \sqrt{B_V^2 + (tS_V)^2}$$

INDEPENDENT VARIABLES (exact values defined by NIST) M_{air} and M_w

DEPENDENT VARIABLES Measured *P, T, \phi, \Delta p* k_b , k_c , C_h , R^*

$$B_{V} = \sqrt{\left(\frac{\partial V}{\partial k_{b}}B_{k_{b}}\right)^{2} + \left(\frac{\partial V}{\partial k_{c}}B_{k_{c}}\right)^{2} + \left(\frac{\partial V}{\partial C_{h}}B_{C_{h}}\right)^{2} + \left(\frac{\partial V}{\partial R^{*}}B_{R^{*}}\right)^{2}} + \left(\frac{\partial V}{\partial P}B_{\rho}\right)^{2} + \left(\frac{\partial V}{\partial P}B_{\rho}\right)^{2} + \left(\frac{\partial V}{\partial T}B_{\tau}\right)^{2} + \left(\frac{\partial V}{\partial \Delta \rho}B_{\Delta \rho}\right)^{2} + \left(\frac{\partial V}{\partial \phi}B_{\phi}\right)^{2}}$$

$$S_{V} = \sqrt{\left(\frac{\partial V}{\partial P}S_{P}\right)^{2} + \left(\frac{\partial V}{\partial T}S_{T}\right)^{2} + \left(\frac{\partial V}{\partial \Delta p}S_{\Delta P}\right)^{2} + \left(\frac{\partial V}{\partial \phi}S_{\phi}\right)^{2}}$$



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Uncertainty in test sensor output

$$U_{IUT} = \sqrt{B_{IUT}^2 + (tS_{IUT})^2}$$

Type B errors are acquired from data acquisition system.
 Type A errors are quantified by the standard deviations in the test sensor reading.

Uncertainty in calibration linearity

$$U_{LR} = \sqrt{(tV_{res})^2}$$







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Calibration Uncertainty for the C3 Anemometer







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Summary

Key Considerations for an Anemometer Calibration Program

- 1) Perform tests in a controlled, uniform-flow, lowturbulence wind tunnel as required by test standards
- 2) Verify wind tunnel performance through velocity surveys
- 3) Qualify ability to perform wind sensor calibrations
 - Blockage evaluation
 - Test repeatability
 - Interlaboratory comparison
- 4) Document the uncertainty analysis

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