

# **Exploring Detection of Multilayer Clouds and Retrieval of Their Properties Using Multispectral Satellite Data in an Artificial Neural Network Approach**

Patrick Minnis<sup>1</sup>, Gang Hong<sup>2</sup>, Szedung-Sun-Mack<sup>2</sup>,  
William L. Smith, Jr.<sup>1</sup>, Yan Chen<sup>2</sup>, Fu-Lung Chang<sup>2</sup>

<sup>1</sup>NASA Langley Research Center, Hampton, VA

<sup>2</sup>SSAI, Hampton, VA

*Joint 21<sup>st</sup> AMS Satellite Meteorology, Oceanography and Climatology Conference  
Madison, WI, 15-19 August 2016*



# Background

- Multi-layered (ML) cloud systems are common feature around the globe
  - ML systems are sloppy, rarely meet our idealizations
- ML systems affect the satellite retrieval of cloud properties using a single-layer (SL) cloud assumption
  - impact the cloud top height (CTH) retrieval
    - retrieve effective height from VIS-IR methods
    - retrieve top of highest cloud layer in IR methods
  - distort cloud distribution and the atmosphere-surface radiation budget
  - makes direct model comparisons and assimilations more uncertain
- Variety of methods developed to passively detect and retrieve ML clouds

## Detection

- Pavolonis & Heidinger (JAM, 2004) BTD(11-12) + VIS
- Wind *et al.* (JAMC, 2010) 0.94  $\mu\text{m}$  +CO<sub>2</sub> slicing
- Joiner *et al.* (AMT, 2010) UV +VIS-IR

## Detection & Retrieval

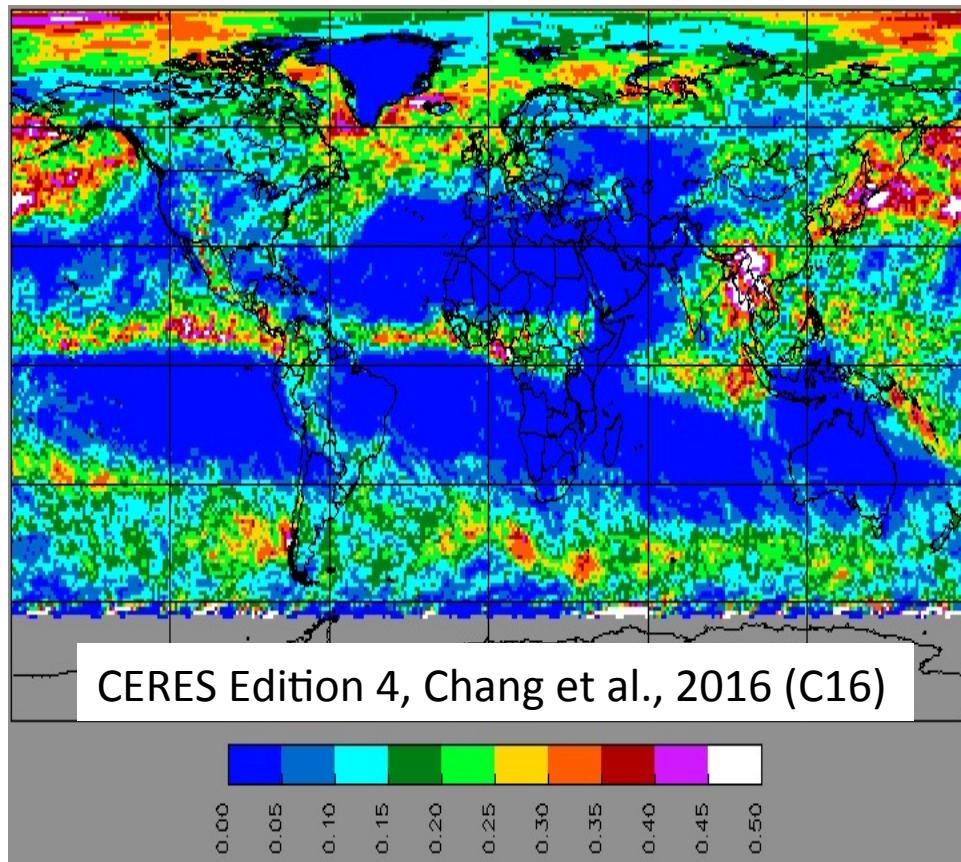
- Lin *et al.* (JGR, 1998) VIS-IR, MW
- Chang & Li (JGR, 2005) VIS-IR, CO<sub>2</sub>-slicing (assumes low cloud from environs)
- Minnis *et al.* (2007) VIS-IR, MW ocean only
- Watts *et al.* (JGR, 2012) 9 channel VIS, IR, CO<sub>2</sub> Optimal Estimation
- Chang *et al.* (2016, in prep) VIS-IR, CO<sub>2</sub>-slicing (retrieves low cloud directly)



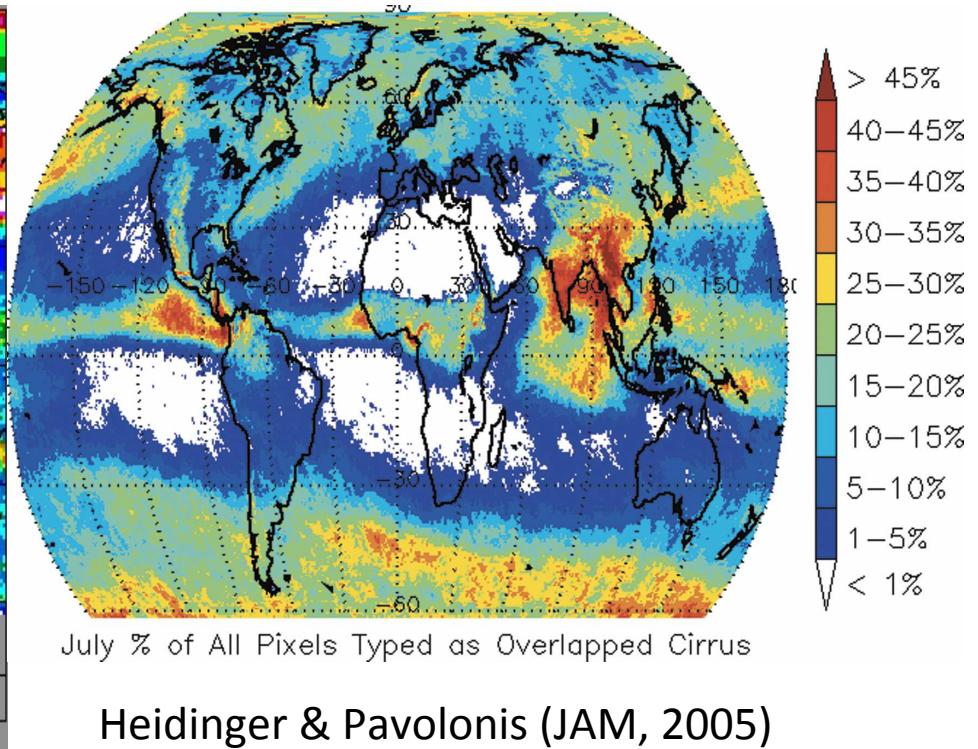
# Global Distributions of Multilayer Cloud Occurrence



Aqua MODIS, July 2002



AVHRR, July 1982, 86, 91, & 98



- Patterns and magnitudes similar between the methods, and are reasonable
  - H&P compared to several other datasets: reasonable
- Some regional differences due to method and years used



## PROBLEM?

- CERES ML identifies ML clouds at 83% compared to 2-layer CALIPSO-CloudSat ice-over-water, upper layer cloud optical depth  $\tau > 0.3$ 
  - only 3.2% of all daytime cases *Viúdez-Mora et al. (CERES STM, 2016)*
- Despite very reasonable monthly averages, CERESML has many false positives when compared 1:1 with CALIPSO-CloudSat profiles mainly due to ice clouds being thicker than the CO2-slicing COD retrieval
  - 53% overestimate
- Need to reduce the overestimation by identifying thick ice clouds that are either contiguous or overlapped lower water clouds & improve missed ML pixels

## APPROACH

- Identify thick ice clouds with 3-channel daytime Ice Cloud Optical Depth from Infrared using a Neural network (ICODIN-3a) *Minnis et al. (JGR, 2016)*
- Screen out contiguous clouds using ICODIN-3a results
- Explore use of direct NN method (LANN) to detect ML conditions



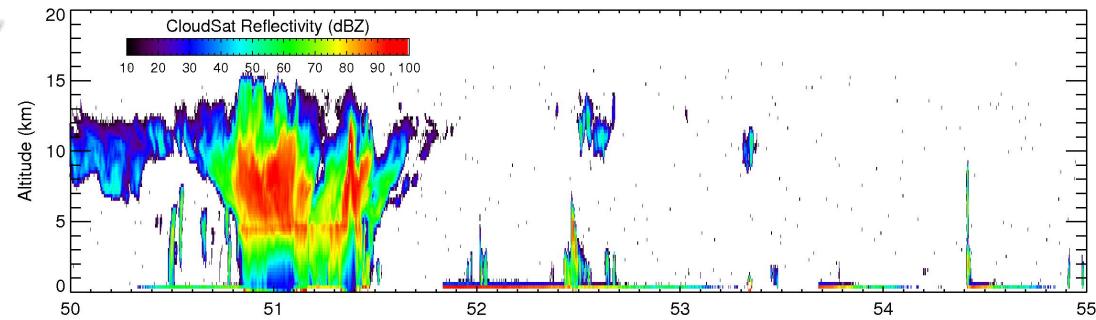
## Data

- C3M (CALIPSO, CloudSat, CERES, MODIS)
  - CALIPSO V3.3 Vertical Feature Mask and optical depth,  $\tau_{\text{CL}}$
  - CloudSat CPR CLDCLASS vertical mask & CWC,  $r_e$ 
    - $\tau_{\text{CS}} = 0.75 * \sum (\text{CWC}/r_e \rho) Q_e \Delta z,$
    - *use only layers where  $T < 253 K$*
  - compute merged CloudSat-CALIPSO ice optical depth,  $\tau_{\text{CC}}$
  - CERES Edition 4 Cloud Retrievals (revised VISST applied to MODIS)
    - includes multilayered clouds, CERES MCOAT Multilayer Cloud Detection (CEML)
      - *CO<sub>2</sub> slicing to estimate cloud emissivity  $\varepsilon$  & CTP above 600 hPa*
      - $\tau_{\text{CO}_2} = 2 * \ln(1 - \varepsilon)$  at nadir
      - *optical depth & phase from VISST,  $\tau_v$*
- Use only daytime, 60°N – 60°S, October 2009
- Compute ICODIN-3a optical depth,  $\tau_{\text{NN}} = f(\text{LAT}, \text{LON}, T_{11}, BTD_{1112}, BTD_{6711})$ 
  - only for  $\tau_v > 4$ , ice phase

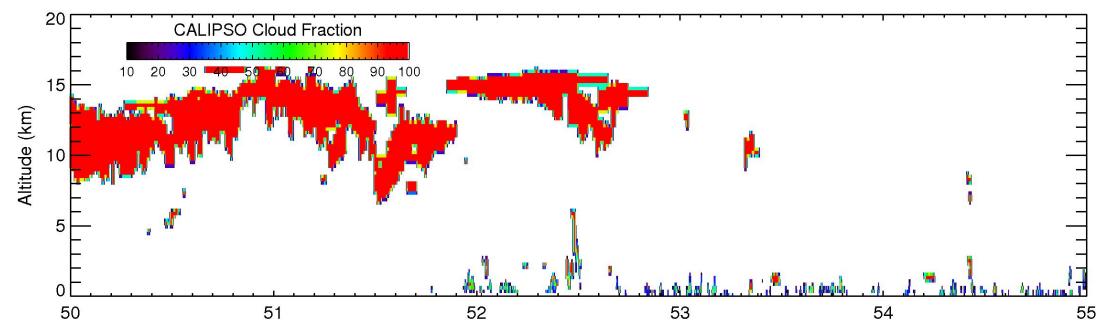
*Kato et al. (JGR, 2011)*

*Chang et al. (2016)*

*Minnis et al. (JGR, 2016)*

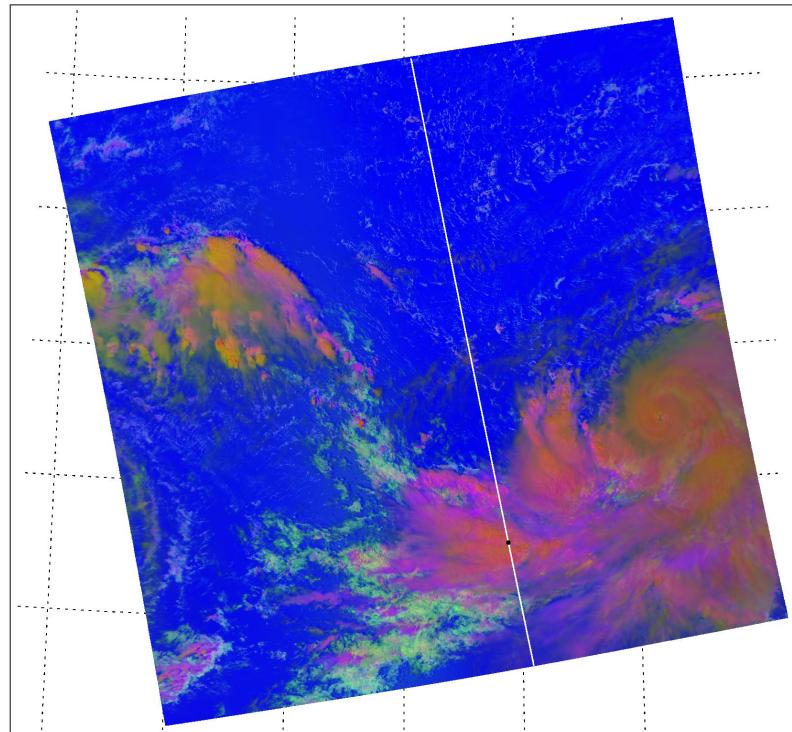


CloudSat Reflectivity



CALIPSO Cloud Fraction

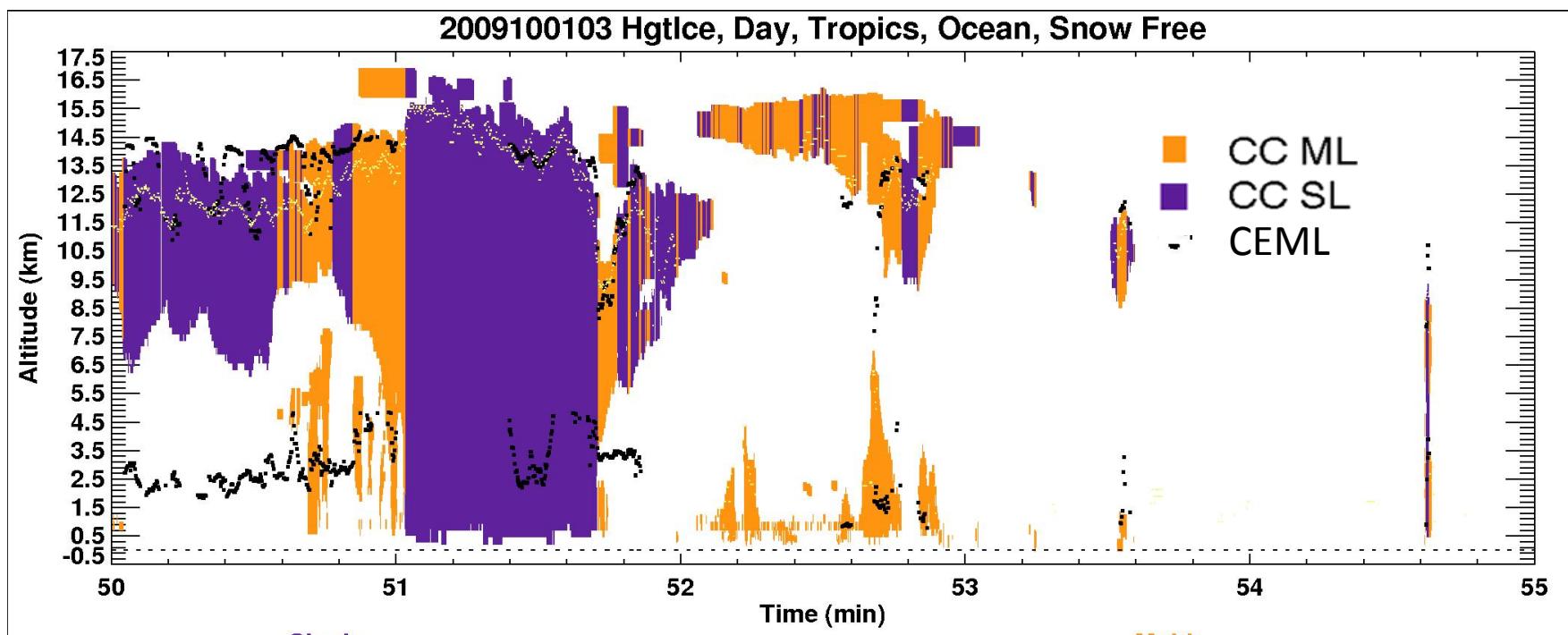
OCT-01-2009 03:50-03:55





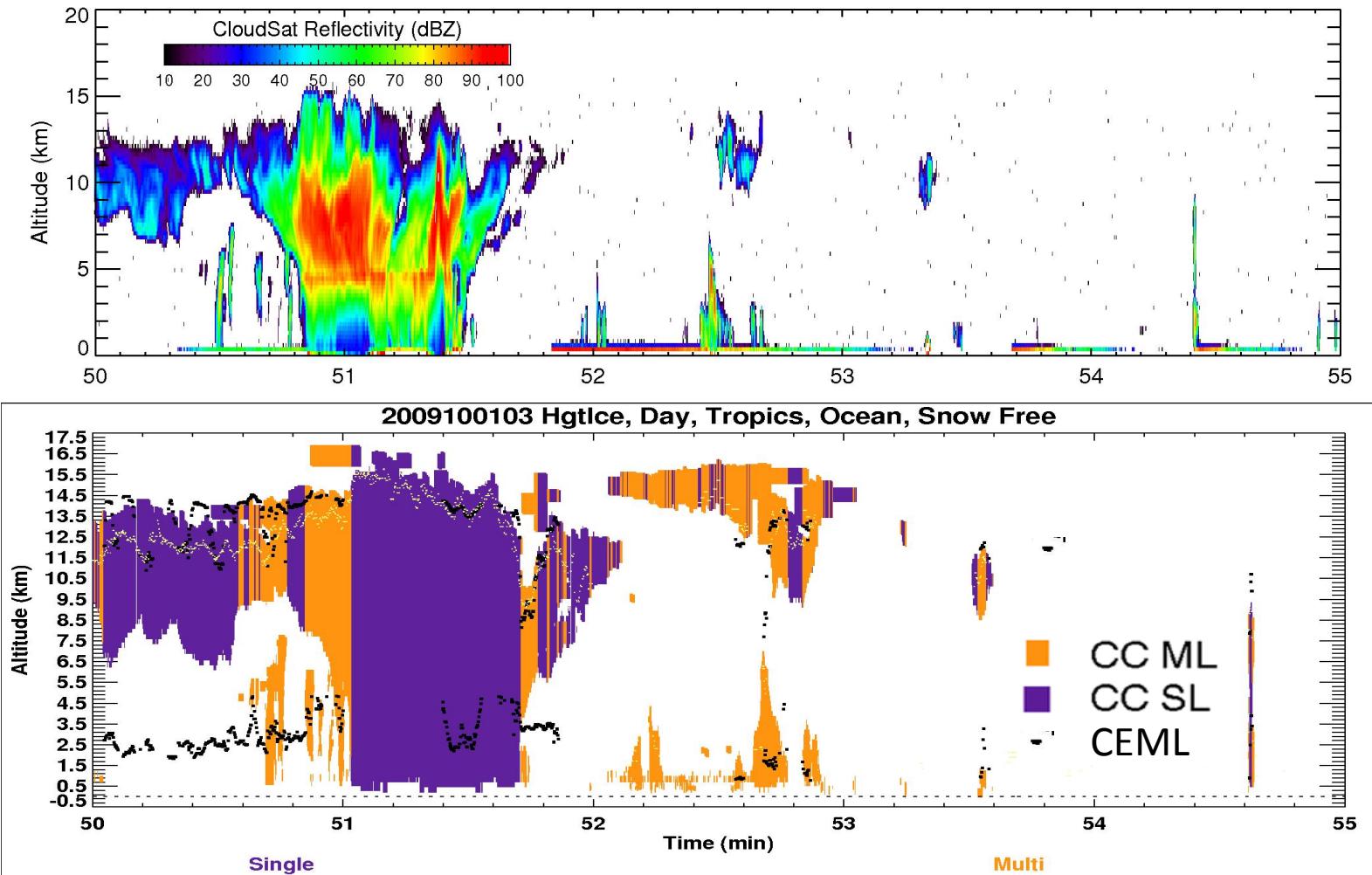
# Defining a Multilayered Cloud System

- **Ice** cloud over **water** cloud with minimum 1-km separation
  - separate ice cloud layers comprise 1 layer
  - separate water layers = 1 layer
  - ice over water with no 1-km separation = single layer (SL)
  - no ice = SL water (not counted here); no water = SL ice
- “Truth” is CALIPSO-CloudSat profile from C3M product





# Multilayer Detection from CALIPSO-CloudSat Not Perfect



- Lowest clouds difficult for CloudSat to identify
  - some errors likely in truth set



# Summary of CERES-ML vs CALIPSO-CloudSat Layering

## Daytime October 2009

### Overall Results, in %, N = 5.1 million with CC ice layer

Classification	CC SL	CC ML
CERES SL	41.5	35.1
CERES ML	11.8	11.6

- Percent correct: 53.1; Percent wrong: 46.9; FAR = 22%
- CERES ML coverage is only half of CC coverage,  
only  $\frac{1}{4}$  of true coverage

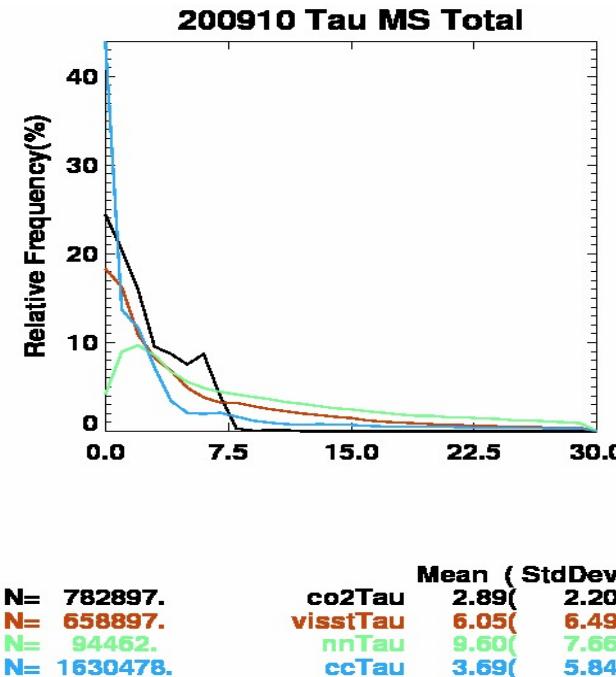
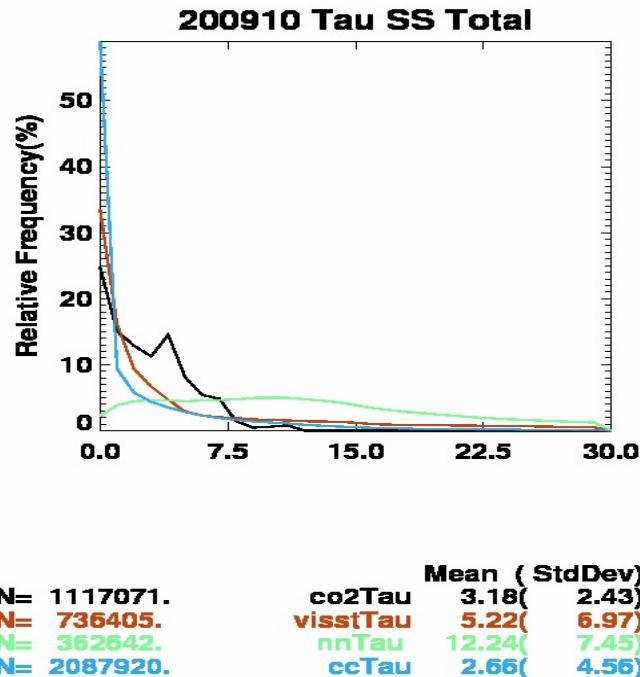
### CC ML only, in % of 5.1 million with CC ice layer

Classification	$\tau(CC) < 0.3$	$\tau(CC) \geq 0.3$
CERES SL	16.2	18.9
CERES ML	0.6	11.0

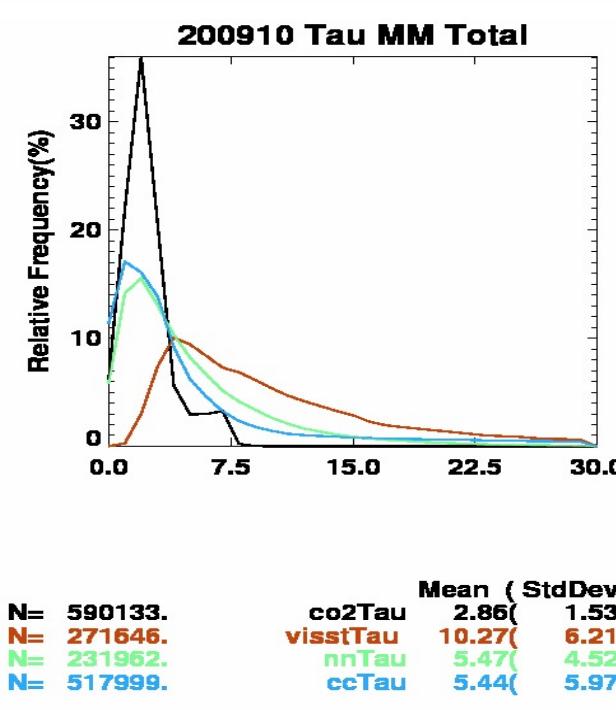
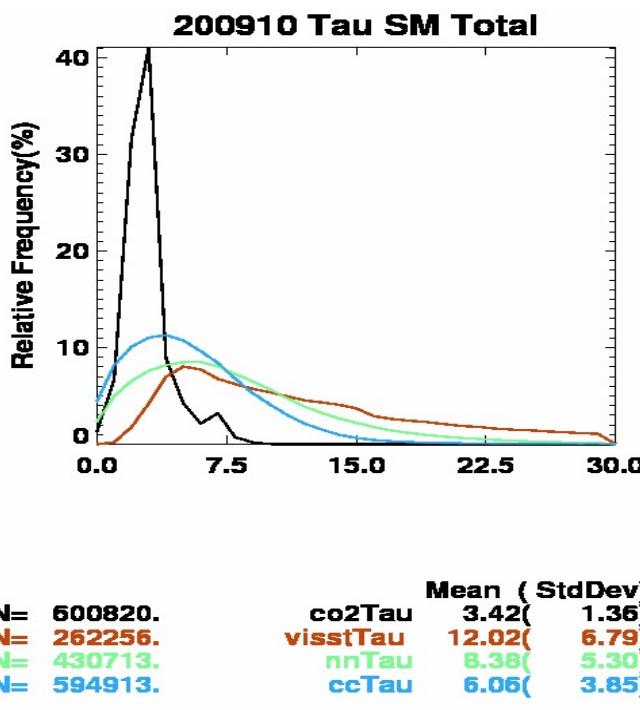
- Nearly half of missed ML clouds due to low  $\tau$  of ice layer  
- do not expect CO<sub>2</sub> to get many  $\tau < 0.3$
- The other half missed due to either upper layer too thick or  
lower layer too thin

C3M  
Oct 2009  
Tau  
Histograms

CC-Single  
CEM Single



CC-Single  
CEM Multi

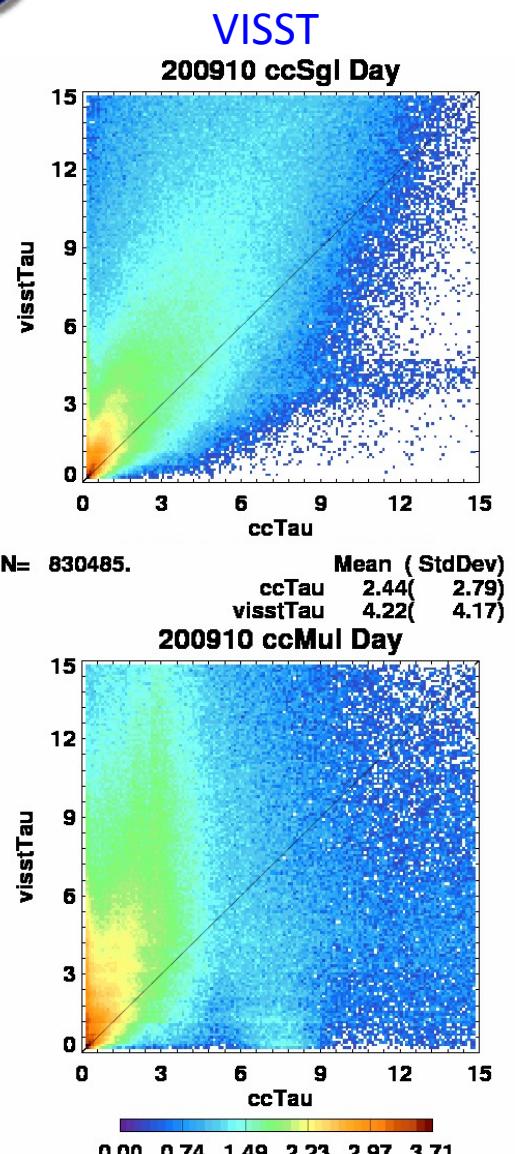


CC-Multi  
CEM Single

CC-Multi  
CEM Multi

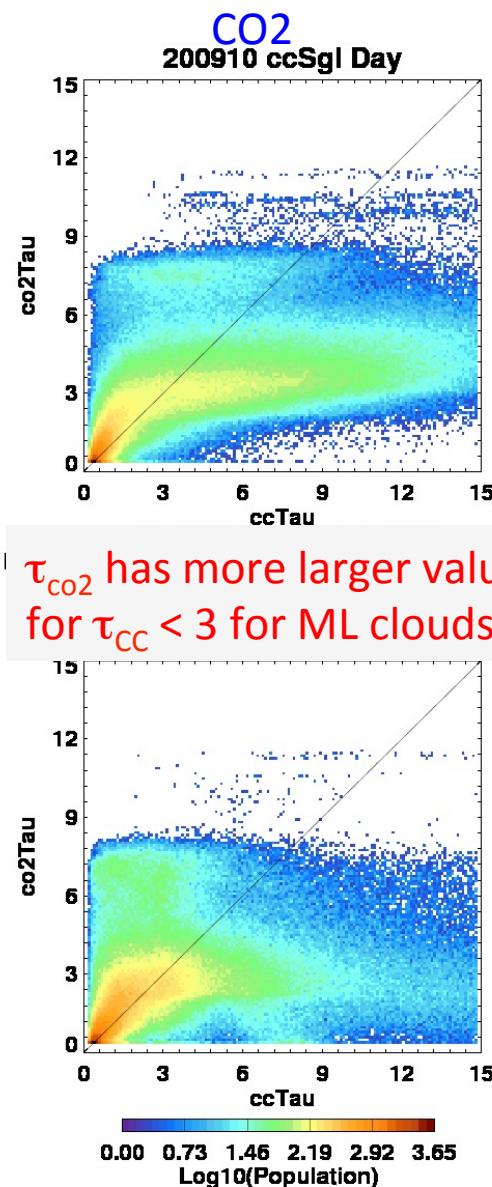


# Bivariate Distributions of Passive vs CC Optical Depths, October 2009

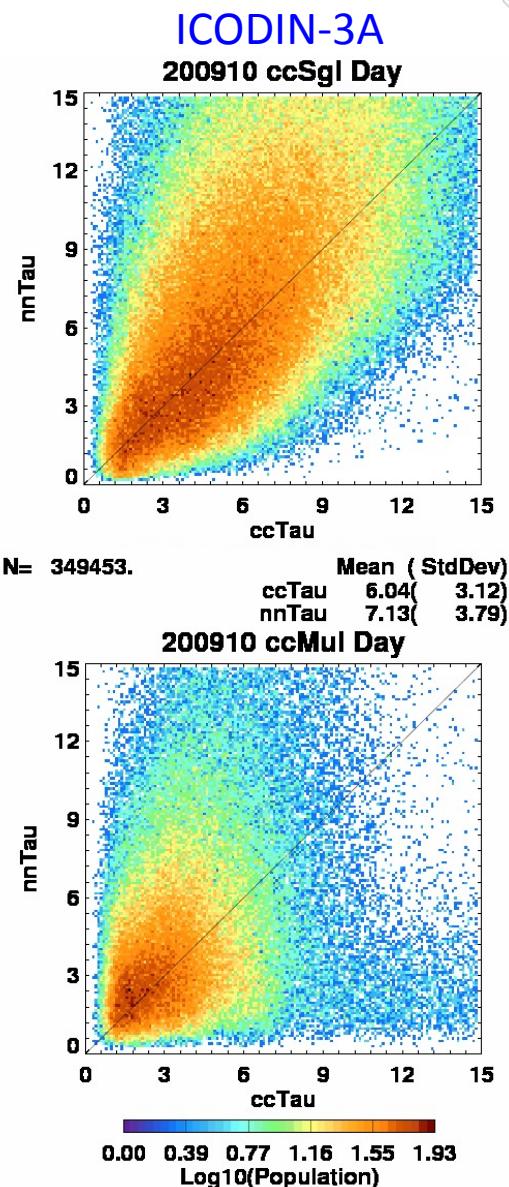


$\tau_v$  more than 2x & less correlated w/  $\tau_{CC}$  for ML clouds

RMS( 4.70).....



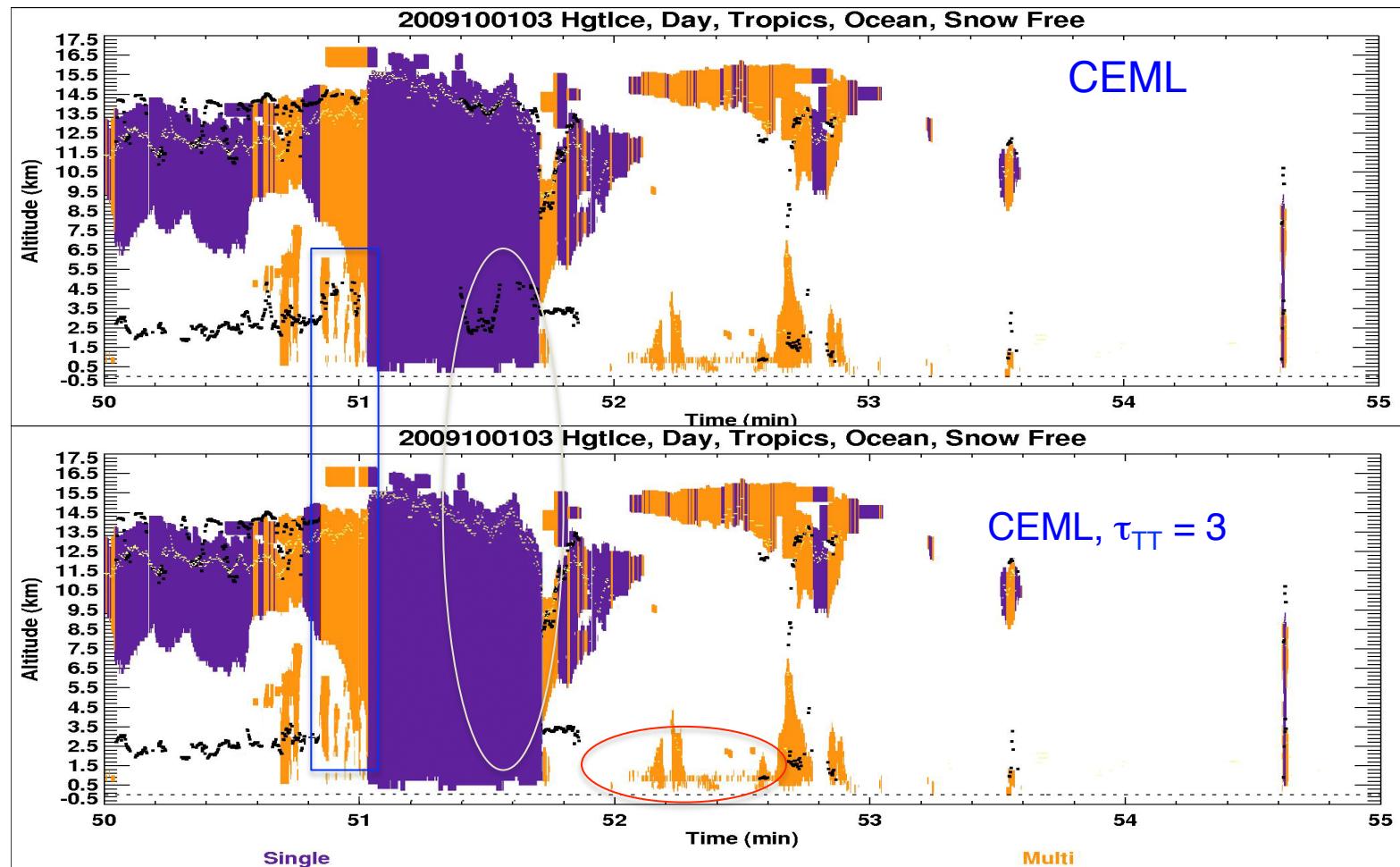
$\tau_{CO_2}$  has more larger values for  $\tau_{CC} < 3$  for ML clouds



$\tau_{NN}$  less correlated w/  $\tau_{CC}$  for ML clouds, tends to be greater



# Screening with ICODIN-3a



- Since CEML assumes it cannot detect ML clouds if upper layer is too thick,
  - reclassify all CEML ML results as SL if,  $\tau_{NN} > \tau_{TT}$ ,
  - $\tau_{TT}$  is thick threshold (TT) optical depth



## Summary of CERES-ML vs CALIPSO-CloudSat Layering

Daytime October 2009

No  $\tau_{TT}$

$\tau_{TT} = 3$

$\tau_{TT} = 4$

$\tau_{TT} = 5$

$\tau_{TT} = 6$

Classification	CC SL	CC ML	FC %	FAR %
CERES SL	41.5	35.1	53.1	22.0
CERES ML	11.8	11.6		
CERES SL	<b>48.8</b>	<b>38.1</b>	57.4	9.4
CERES ML	4.4	8.6		
CERES SL	<b>48.8</b>	<b>37.5</b>	58.0	9.5
CERES ML	5.1	9.2		
CERES SL	<b>47.5</b>	<b>35.1</b>	57.2	10.8
CERES ML	5.8	9.7		
CERES SL	<b>46.8</b>	<b>36.6</b>	56.9	12.2
CERES ML	6.5	10.1		

- Optimum threshold is  $\tau_{TT} = 4$
- Still not satisfactory detection rate
- Need to address missed ML cases



# Further Use of the Neural Network Approach

## Layering Neural Network (LANN)

- ICODIN-3a threshold increased fraction correct and reduced false ML detection
  - still no help for the larger error: missed ML clouds
- No obvious signal for missed ML clouds vs. SL clouds
  - try applying neural network directly

### INPUT

- Lat, Lon, SZA
- 0.65 & 2.13  $\mu\text{m}$  reflectance
- 3.8, 6.7, 8.5, 10.8, 12.8  $\mu\text{m}$  brightness temperatures
- $BTD_{3811}, BTD_{3867}, BTD_{6711}, BTD_{8511}, BTD_{1112}$

### OUTPUT

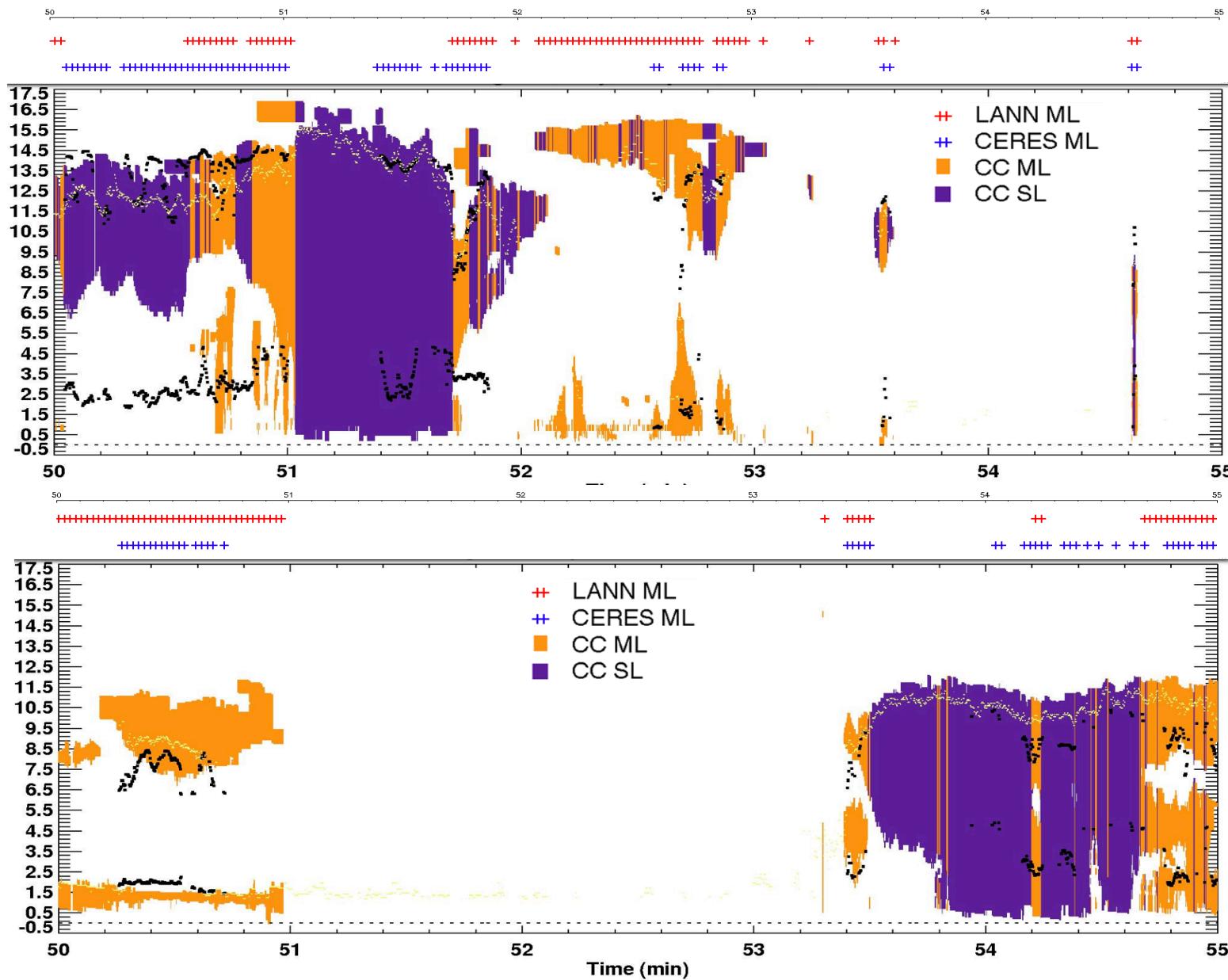
- ML or SL

### TRAINING and VALIDATION

- 1/5 of data for training, 1/5 for validation

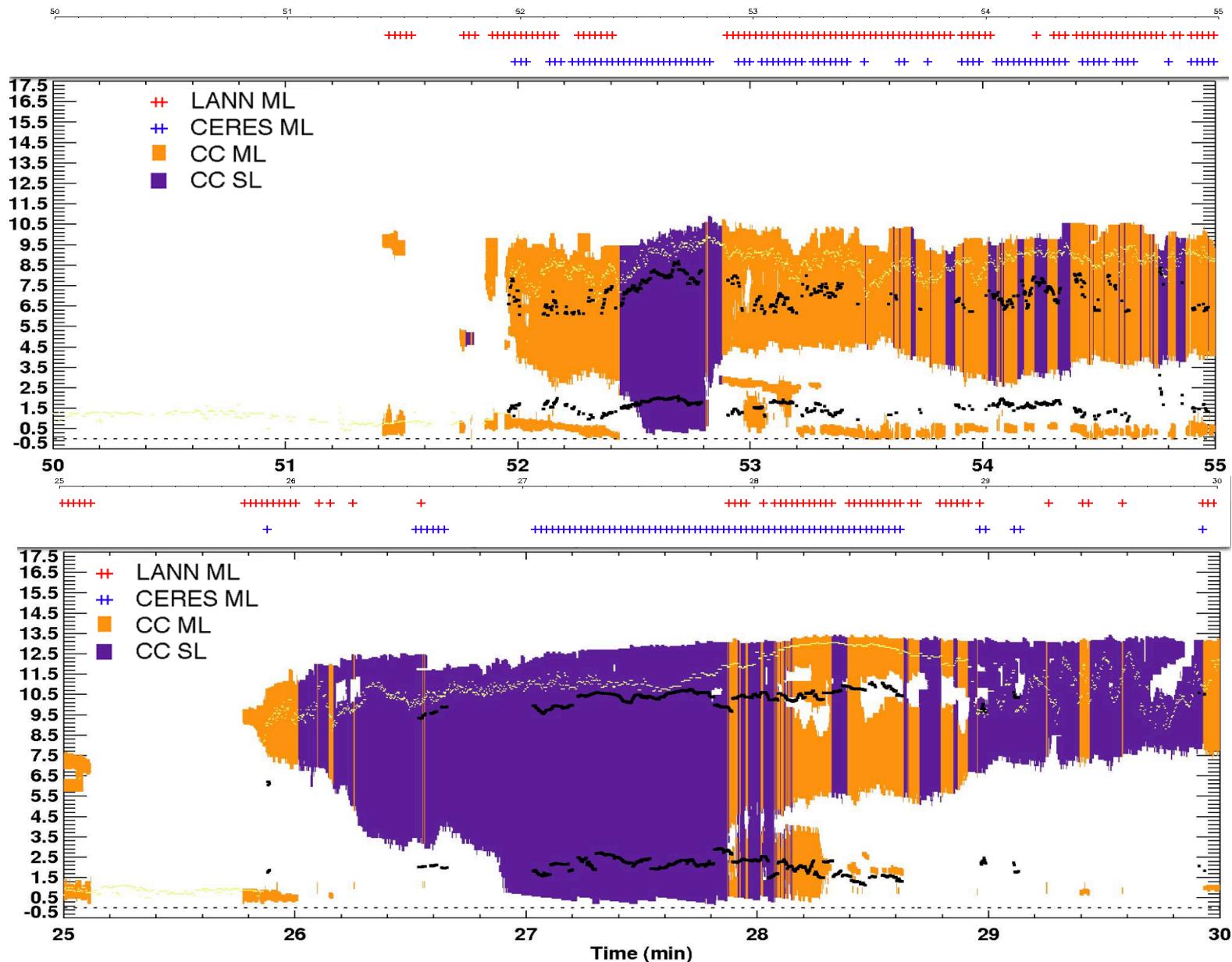


# Examples of Applying Layering Neural Network (LANN)





# Examples of Applying Layering Neural Network (LANN)





# Summary of Neural Net ML vs CALIPSO-CloudSat Layering

## Daytime October 2009

### Overall Results, in % with all CC ice layers

Classification	CC SL	CC ML
CERES SL	49.0	14.0
CERES ML	8.5	28.5

- Percent correct: 77.5; Percent wrong: 22.5; FAR = 17%
- NN ML coverage is 87% CC coverage,  
but only 2/3 of true coverage

### Results in % CC ice layer, for $\tau_{CC} > 0.3$ only

Classification	CC SL	CC ML
CERES SL	45.0	12.0
CERES ML	8.5	34.5

- Percent correct: 79.5; Percent wrong: 20.5; FAR = 15%  
- slightly better than for all ice clouds
- NN ML coverage is 92% of CC coverage,  
only 2/3 of true coverage

## CONCLUSIONS

- Thick ice cloud neural net (ICODIN-3a) increases CERES ML layer FC by 4-5%
  - decreases FAR and total fraction of ML clouds
- Initial test of layering neural network (LANN) very promising
  - increases fraction correct by 25% and even detects ML when  $\tau < 0.3$ 
    - *FC up to 80%*
  - has not been optimized
  - misidentified clouds not yet classified (e.g.,  $\tau$  ranges)

## FUTURE

- Optimize LANN detection
  - assess sensitivity to vertical separation assumption
  - determine which channels are truly needed
  - perform analyses at other viewing angles (matched GEOSat, VIIRS)
  - include 1.38  $\mu\text{m}$  reflectance, NWP analysis data as input
- Test capability of NN method to estimate  $Z_{upper}$ ,  $\tau_{upper}$ , etc.
  - if only one parameter can be determined, other approaches (e.g., MCOAT) will be able to retrieve the remaining parameters