Quantitative precipitation nowcasting using specific differential phase olorado

Results

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Rainfall fields estimated from K_{dp} exhibit approximately twice the predictability as reflectivity-based estimates using ETS

Rain gauge cross-validation showed the benefits of QPE

and CC values when referring to radar-based estimates

using K_{dn} decrease with increasing lead time

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Introduction

- Recent research indicates that using specific differential phase (K_{do}) has several advantages over using reflectivity for estimating rainfall
- This paper presents an evaluation of nowcasting rainfall fields based on K_{dp} estimates relative to reflectivity-based estimates

Data

- Approximately 27 h of data (1593 data frames) collected during the 2009 CASA IP1 were used for evaluation
- Rain gauge cross-validation was performed using data collected by gauges located within the USDA Little Washita **River Experimental Watershed**

Nowcasting methodology

- The Dynamic and Adaptive **Radar Tracking of Storms**
 - (DARTS) algorithm was used to estimate motion between successive estimated rainfall fields
- DARTS represents the general continuity equation as a linear model constructed in the Fourier domain

$$\frac{\partial}{\partial t}F(x,y,t) = -U(x,y)\frac{\partial}{\partial x}F(x,y,t) - V(x,y)\frac{\partial}{\partial y}F(x,y,t)$$





Rain rate fields corresponding to 0055 UTC 31 Mar 2009: (a) initial estimate and (b) corresponding 10-min prediction of rainfall field derived according to $R = 18.15 K_{dp}^{0.791}$, (c) initial estimate and (d) corresponding 10-min prediction of rainfall field derived according to $Z = 300R^{1.4}$





Comparison of nowcasting performance using (a) CC and (b) ETS scores and radar-based estimates as scoring reference





Comparison of nowcasting performance using (a) NB, (b) CC, and (c) NSE scores and rain gauge observations as scoring reference