

# A COMPACT AIRBORNE KA-BAND PRECIPITATION PMS PROBE RADAR (KPR)

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# Background

- 2005: ProSensing developed a compact G-band (183 GHz) water Vapor radiometer (GVR) packaged in a standard PMS probe canister





# Background (cont.)

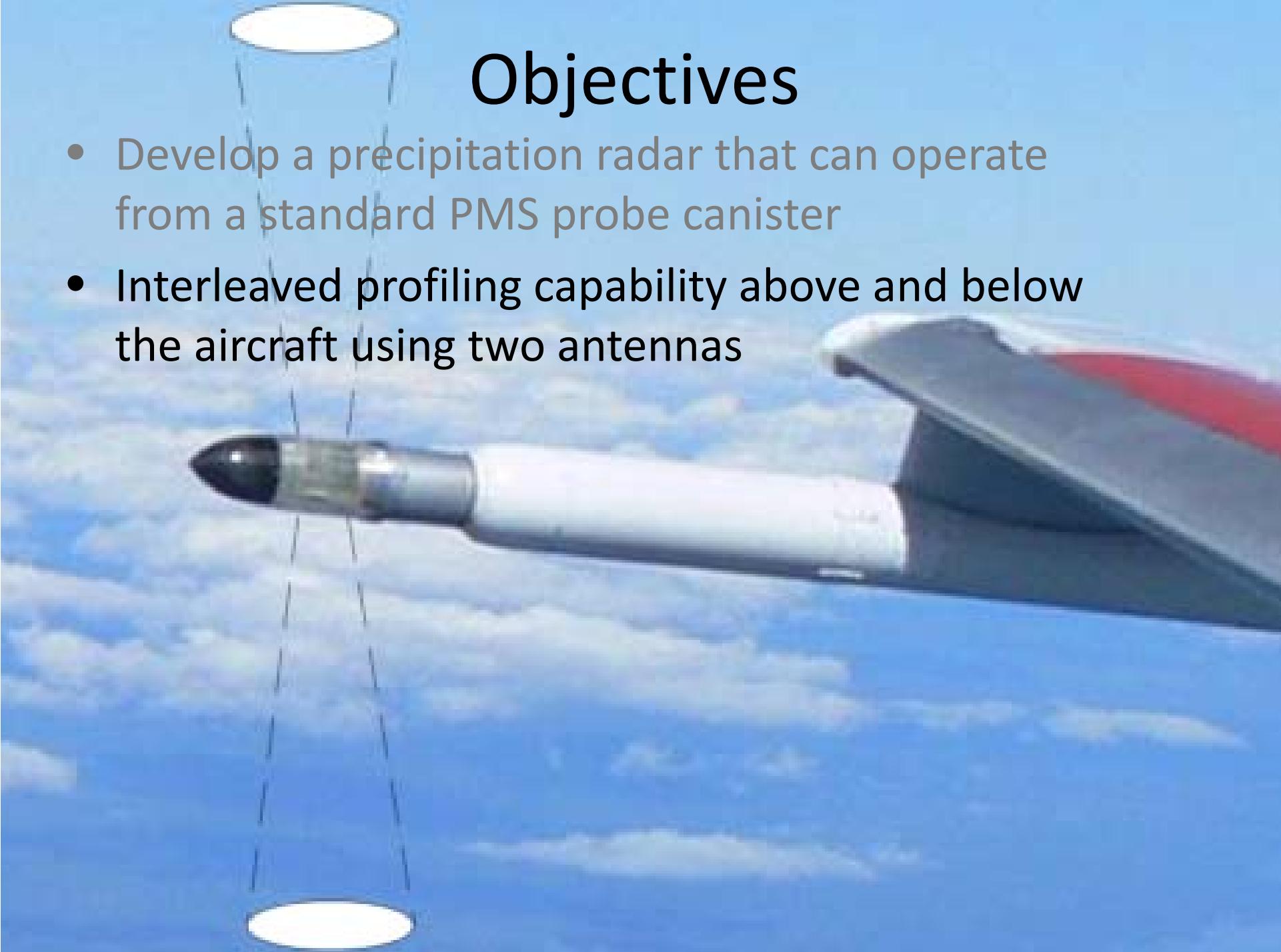
- 2011-2013: ProSensing delivered six compact Ka-band (35 GHz) solid state range finding radars



# Objectives

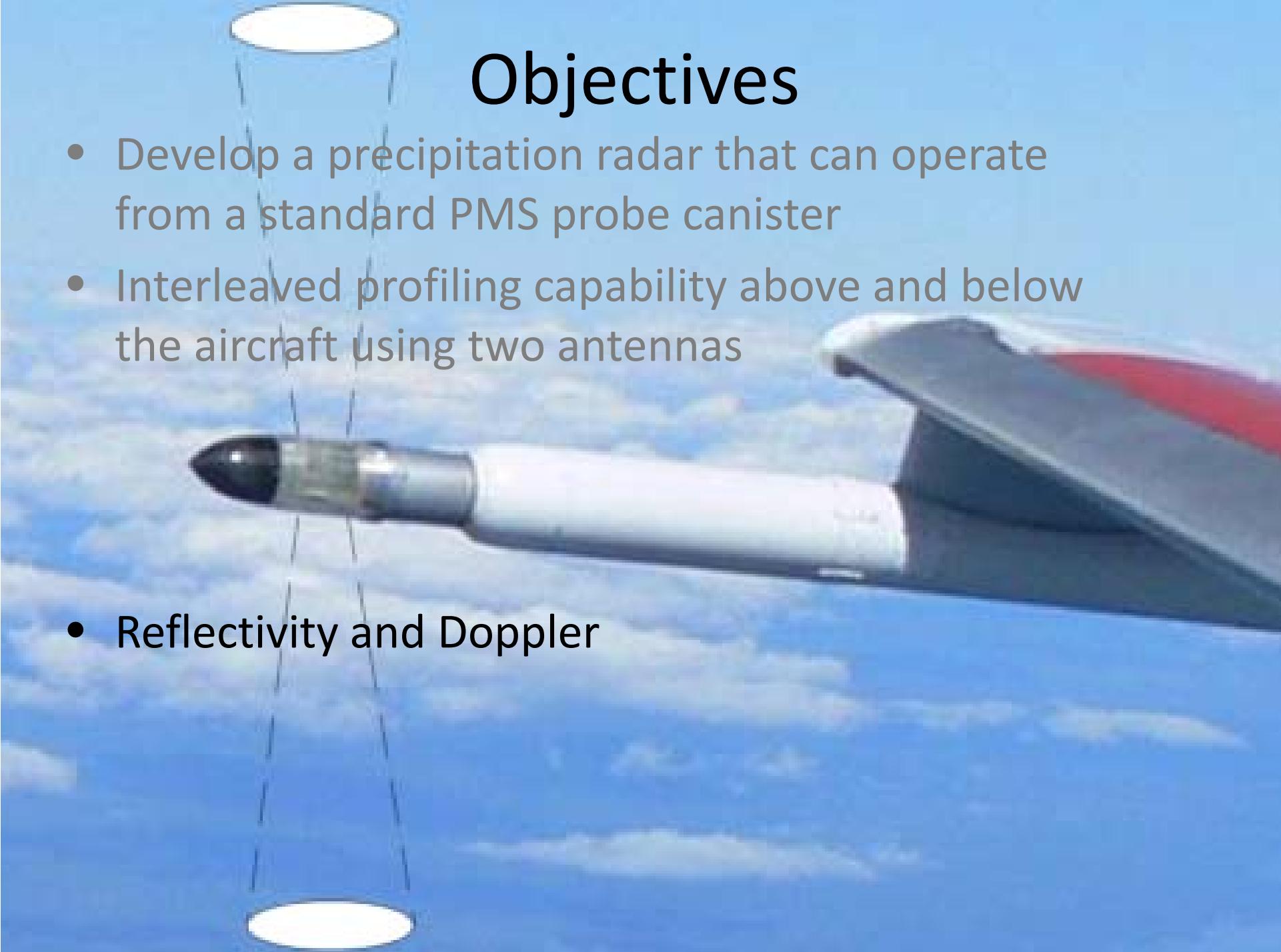
- Develop a precipitation radar that can operate from a standard PMS probe canister





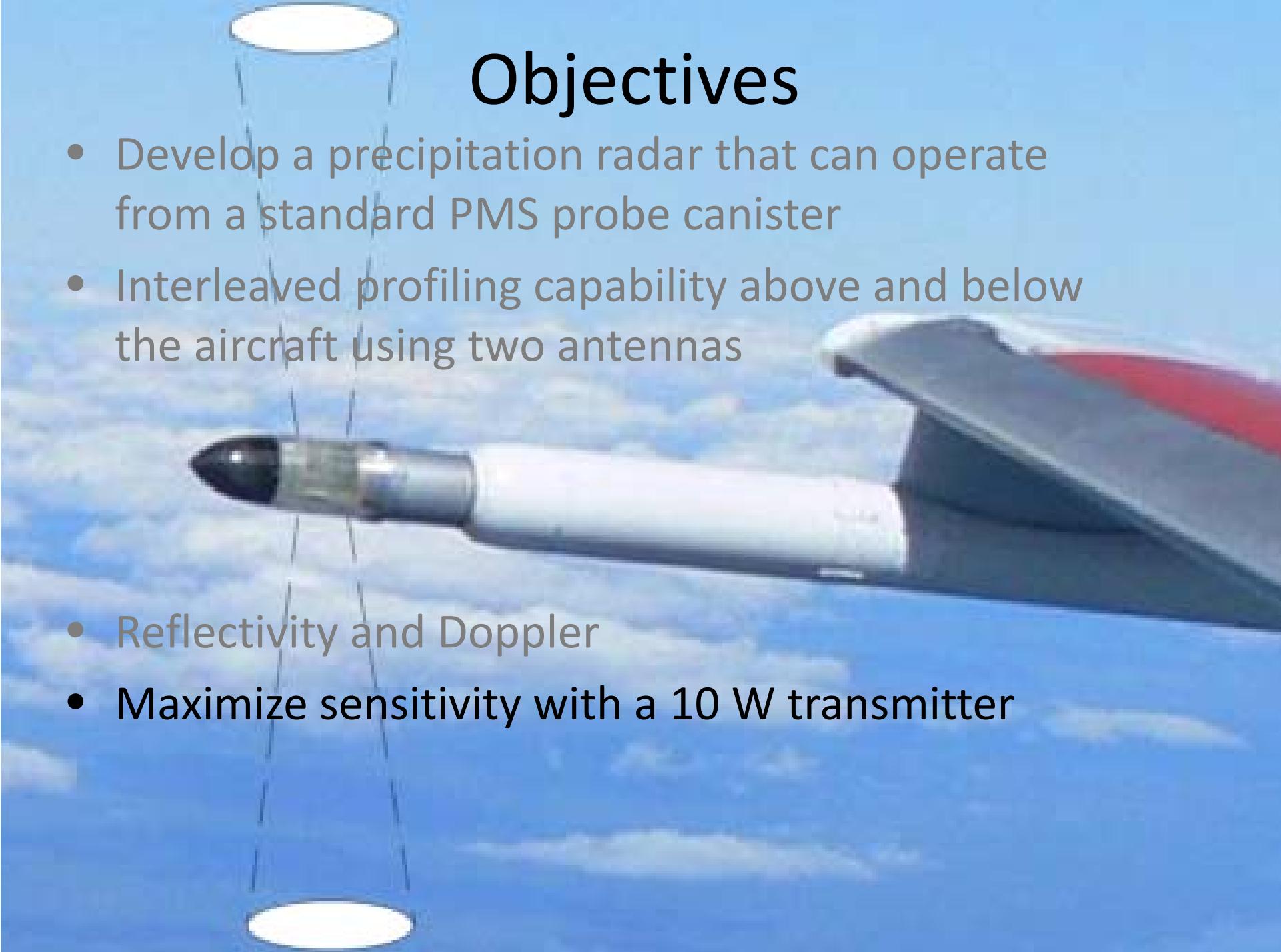
# Objectives

- Develop a precipitation radar that can operate from a standard PMS probe canister
- Interleaved profiling capability above and below the aircraft using two antennas



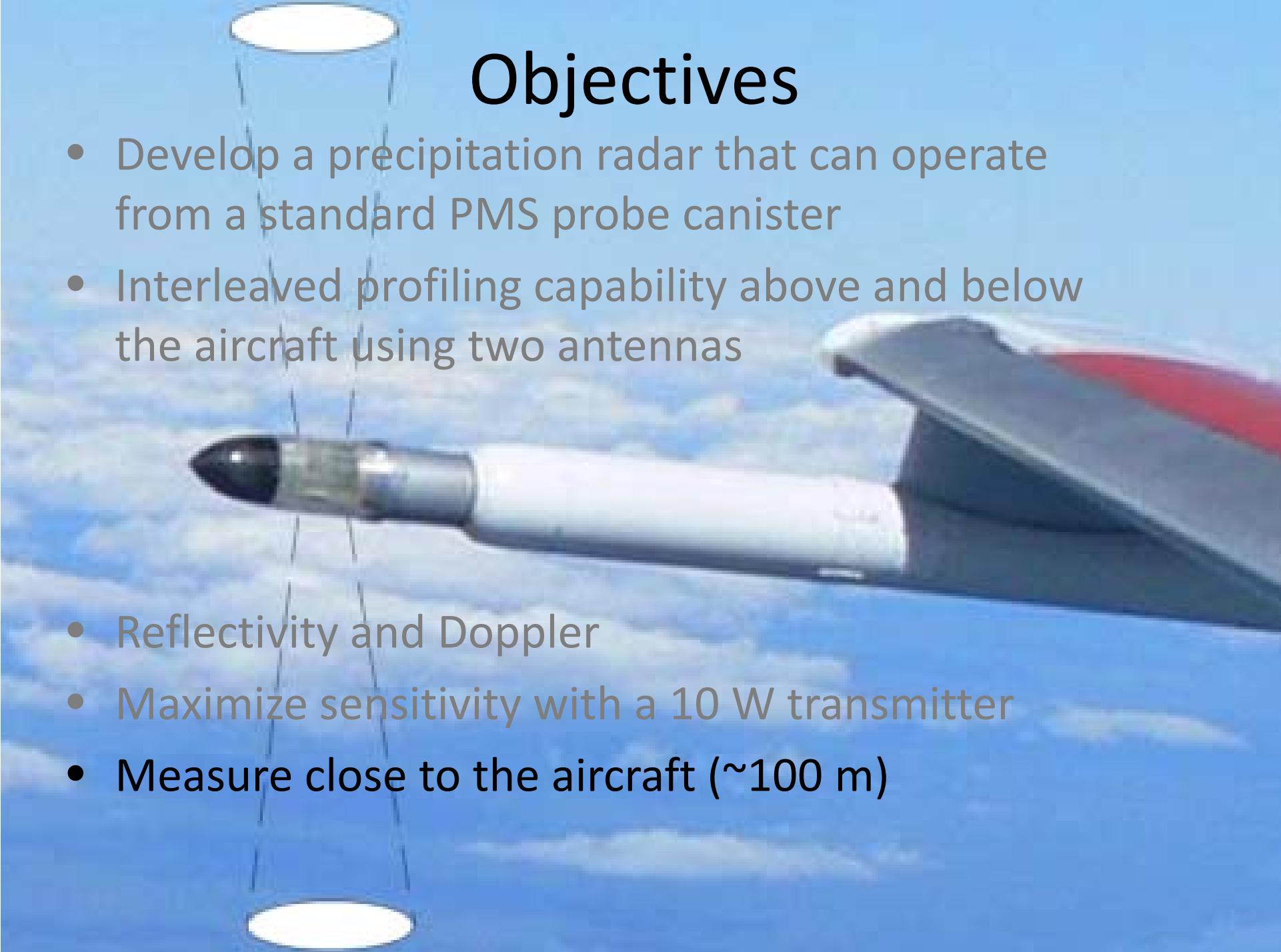
# Objectives

- Develop a precipitation radar that can operate from a standard PMS probe canister
- Interleaved profiling capability above and below the aircraft using two antennas
- Reflectivity and Doppler



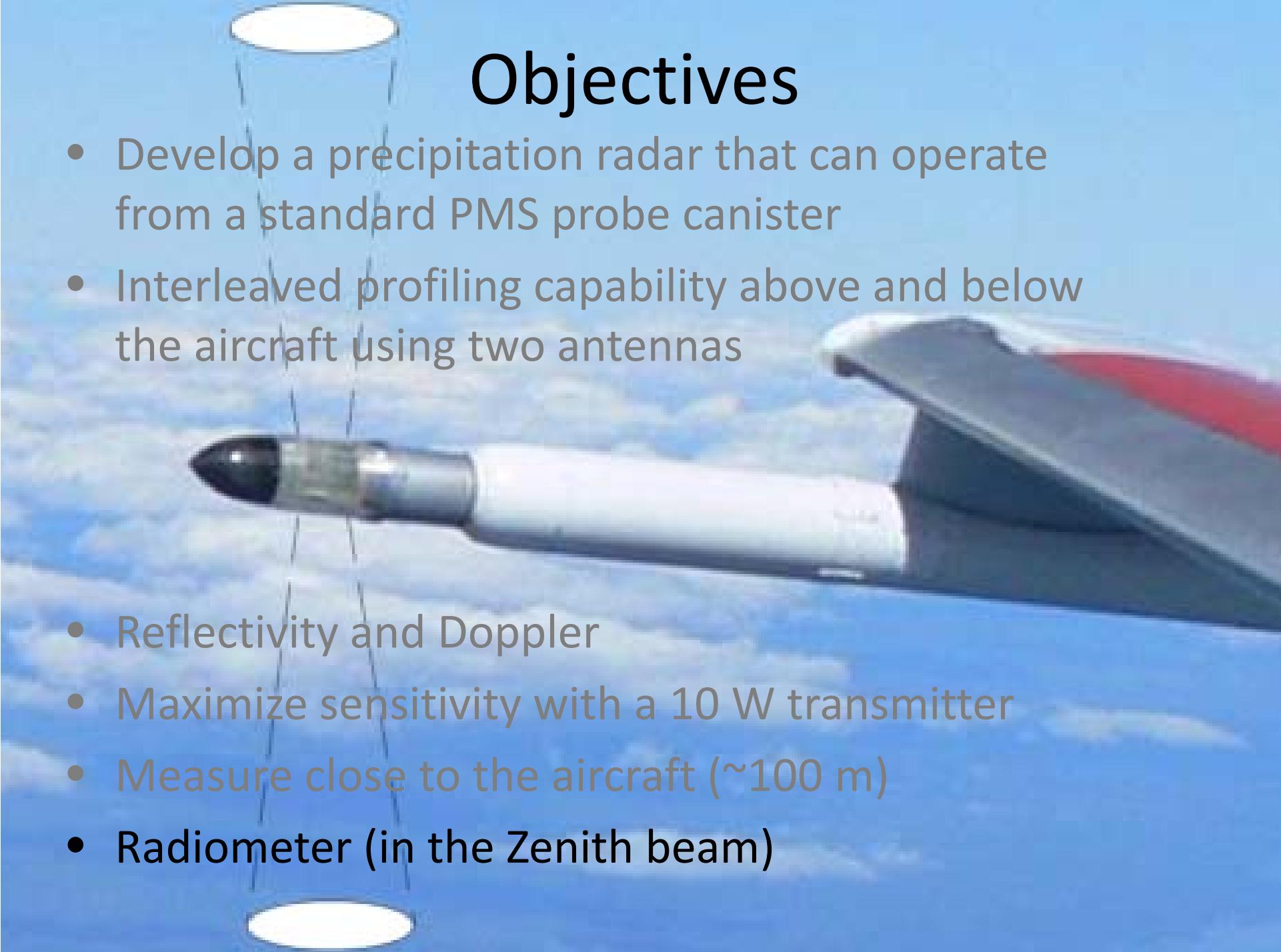
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- Reflectivity and Doppler
- Maximize sensitivity with a 10 W transmitter



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- Measure close to the aircraft ( $\sim 100$  m)
- Radiometer (in the Zenith beam)

# Key Enabling Component

- Compact 10 W, pulsed, solid state Ka-band power amplifier



Size: 5" x 3" x 1"

# Design Features

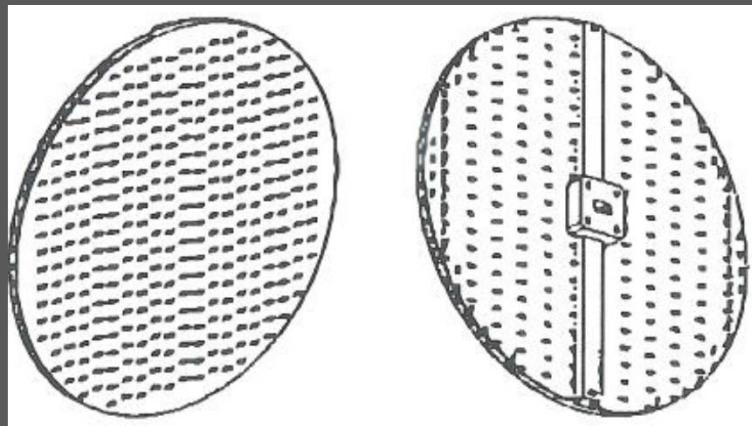
- Interleaved profiling capability above and below the aircraft using two antennas -> T/R switch network and dual-antennas



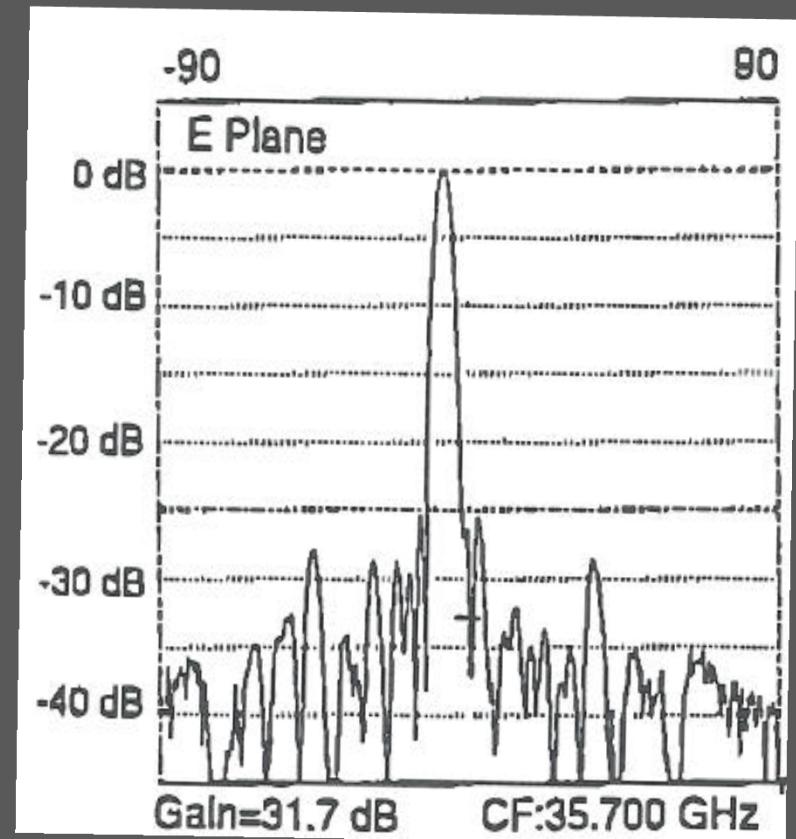
- ~ 0.2 dB loss per junction
- ~ 30 dB isolation per junction
- ~ 200 ns transition time
- 20 kHz max. PRF rate (40 kHz events)

# Design Features

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- Slotted Waveguide Array
- 35.5 – 35.9 GHz Freq. Range
- 4.2 Beamwidth
- 31.7 dB Gain



# Design Features

- Interleaved profiling capability above and below the aircraft using two antennas -> T/R switch network and dual-antennas
- Reflectivity and Doppler measurements -> Integrated Analog Devices ADIS16375 IMU



- 3-axis gyroscope:  $\pm 300^\circ/\text{sec}$
- 3-axis accelerometer:  $\pm 5\text{g}$
- Temperature range:  $-40^\circ\text{C}$  to  $+105^\circ\text{C}$
- Bandwidth: 330 Hz; 2.4 kHz sampling

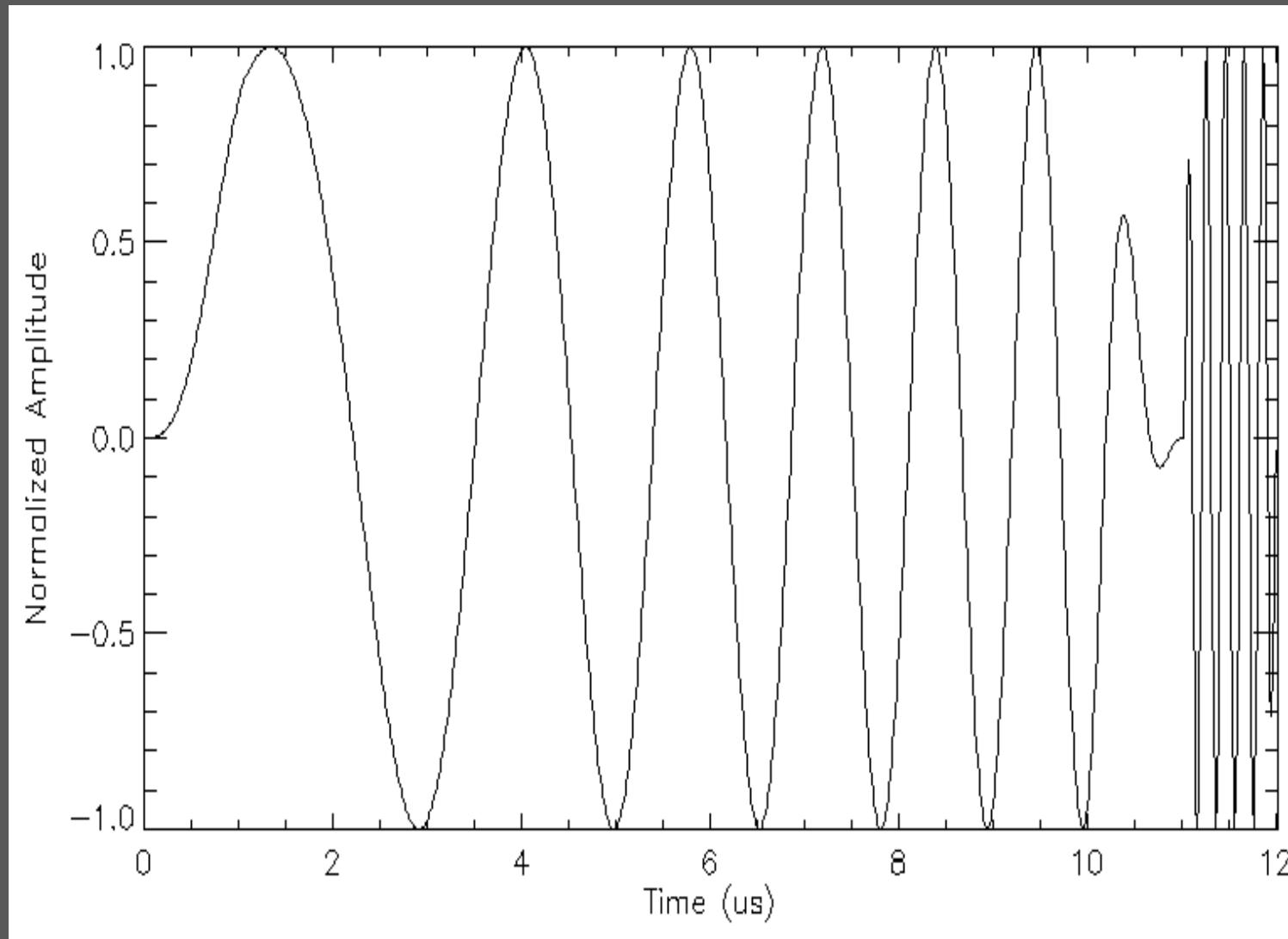
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- Maximize sensitivity with a 10 W transmitter -> Pulse compression

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- Maximize sensitivity with a 10 W transmitter -> Pulse compression
- Measure close to the aircraft (~100 m) -> Combined offset frequency short/chirped TX pulse Wide-band RF; dual-channel IF receiver and data system

# Combined Chirp/Short pulse

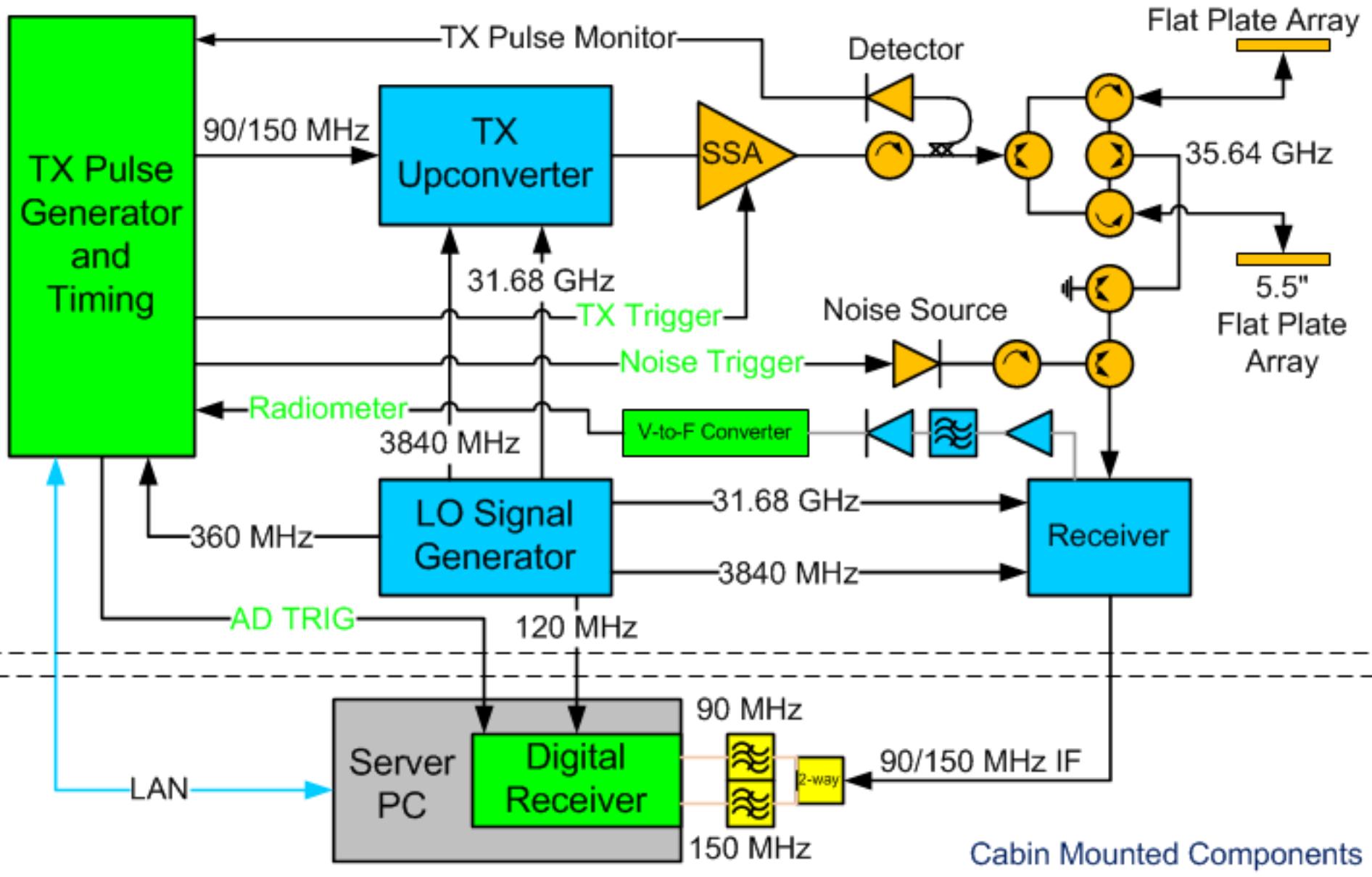


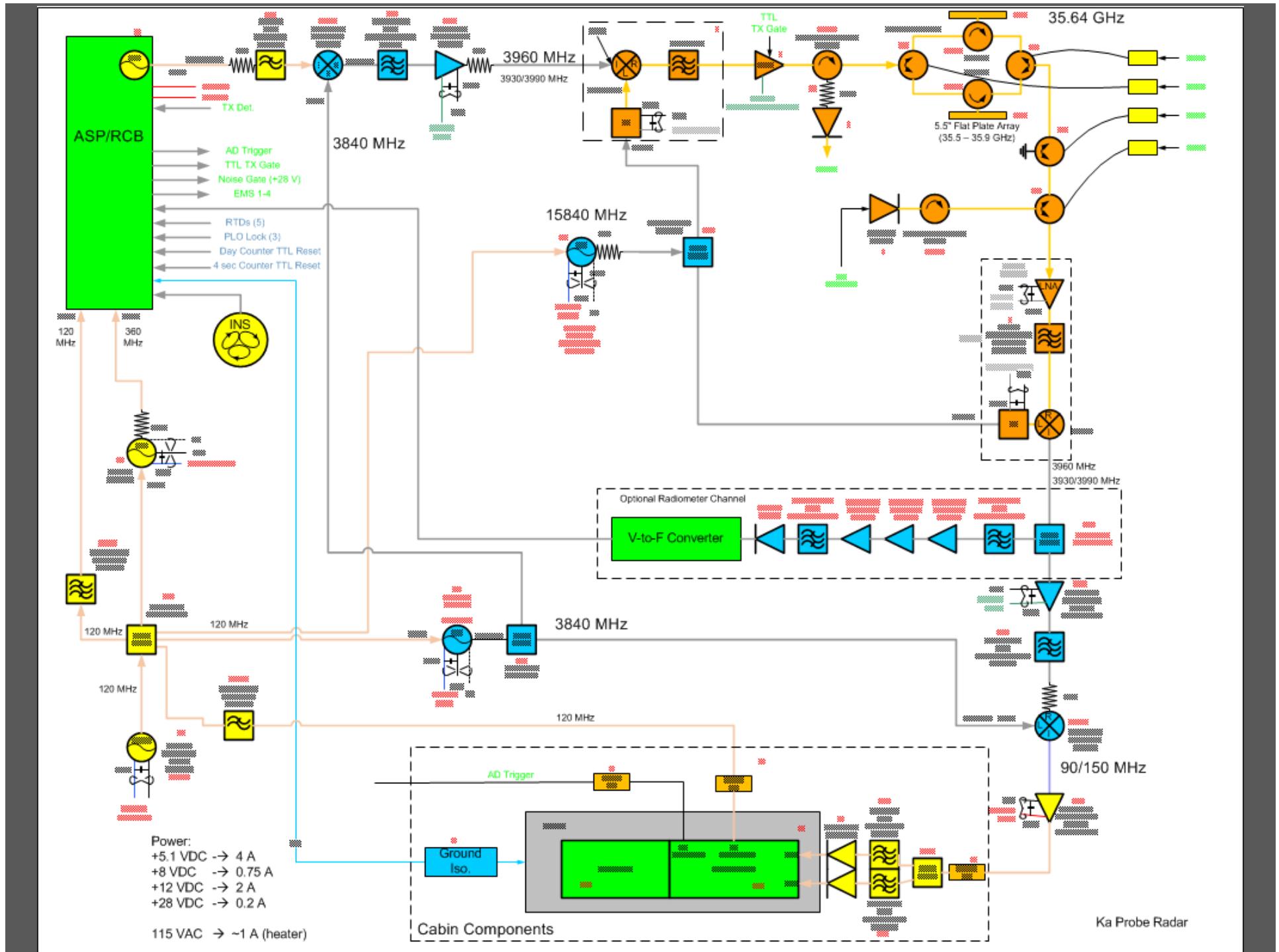
# Design Features

- Interleaved profiling capability above and below the aircraft using two antennas -> T/R switch network and dual-antennas.
- Reflectivity and Doppler measurements -> Integrated Analog Devices ADIS16375 IMU
- Maximize sensitivity with a 10 W transmitter -> Pulse compression.
- Measure close to the aircraft (~100 m) -> Combined offset frequency short/chirped TX pulse.
- Radiometric measurement capability (in Zenith beam) -> Integrated noise source and wide band radiometer receiver

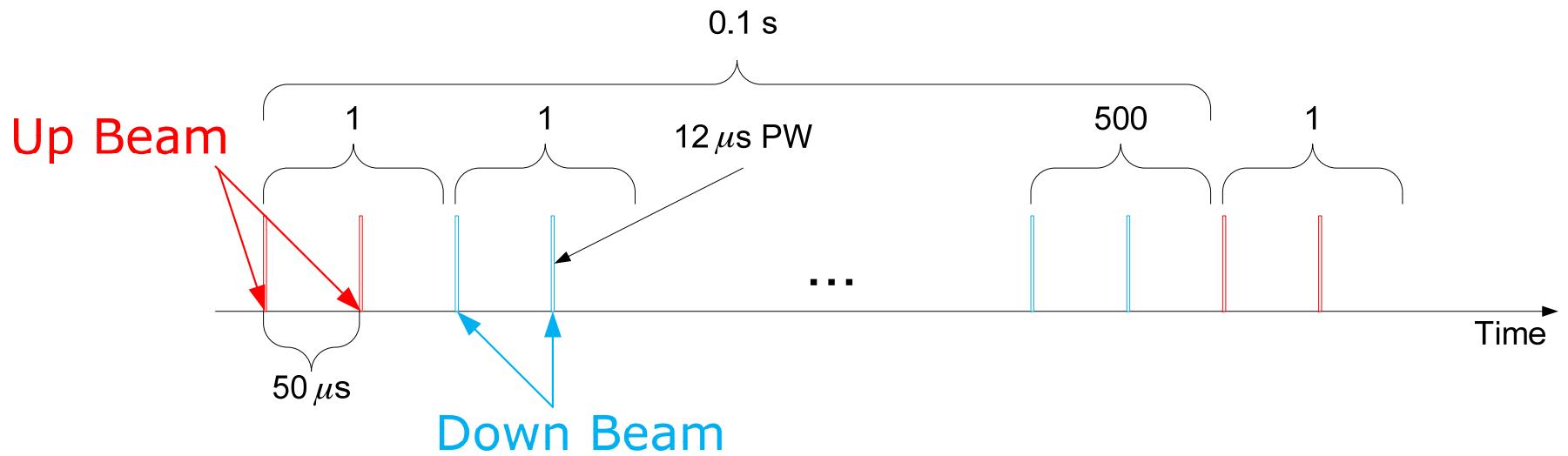
# Simplified Component Level Diagram

## Pod Mounted Components





# Radar Pulsing



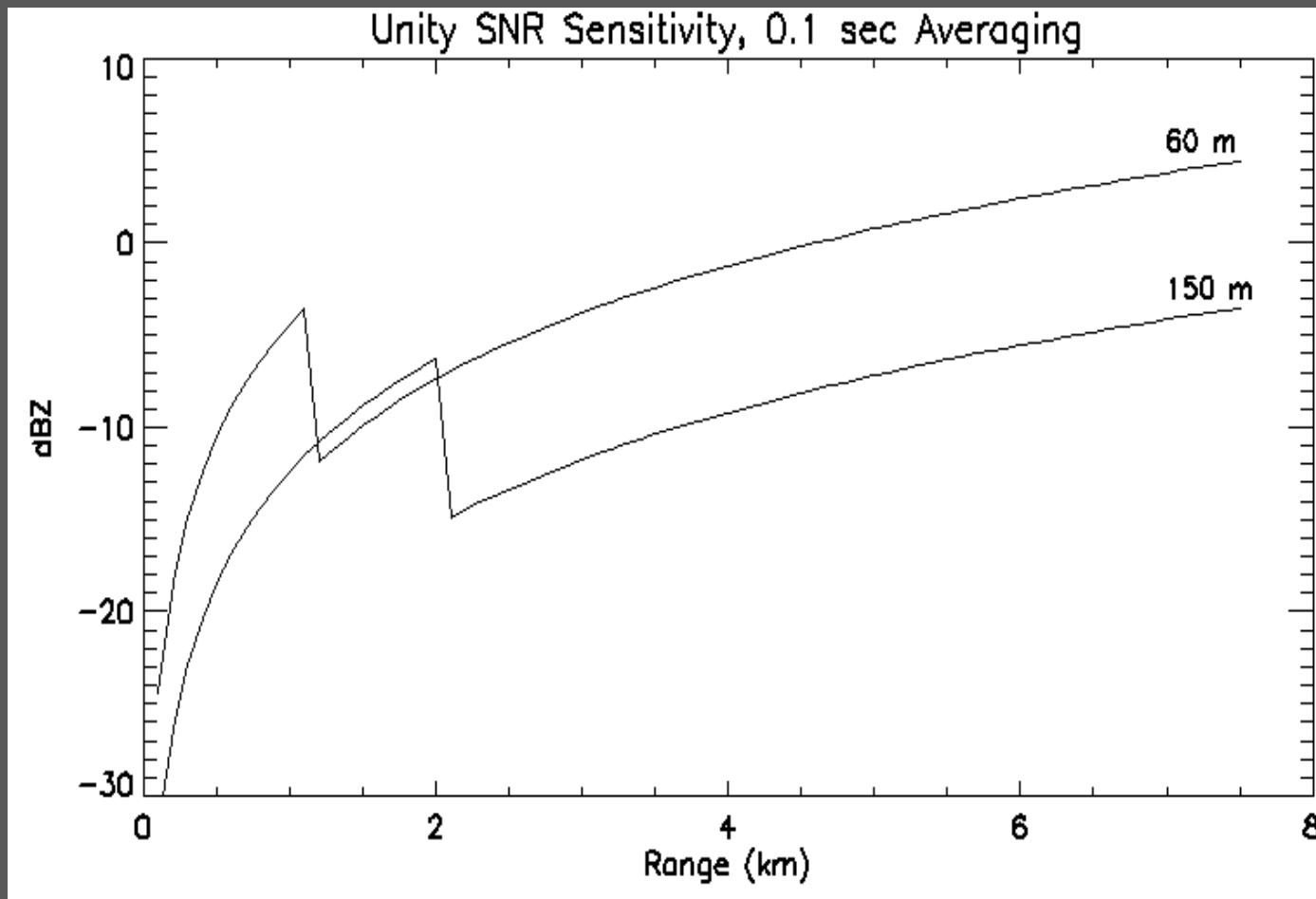
$$PRI = 50 \text{ us} \leftrightarrow \text{PRF} = 20 \text{ kHz}$$

$$\text{Pulse Pair Group Frequency} = 5 \text{ kHz}$$

$$T_{INT} = 0.1 \text{ sec}$$

$$N = 5000 * 0.1 = 500$$

# Sensitivity



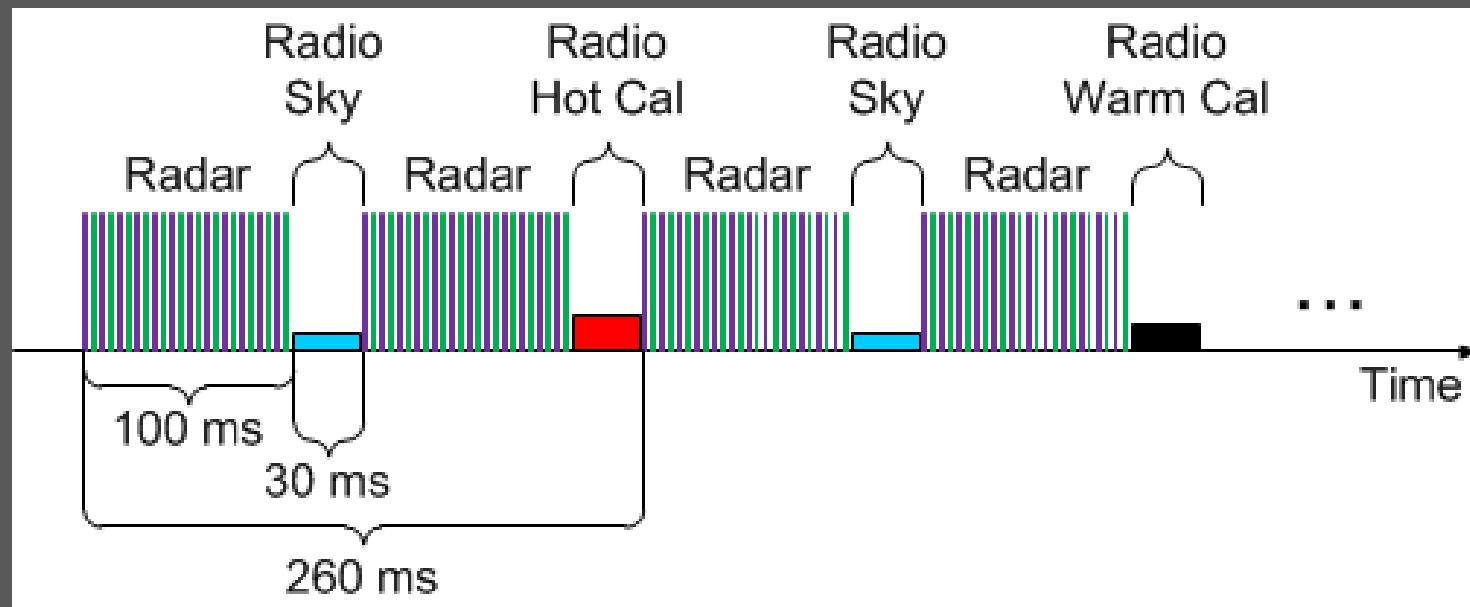
$P_t = 40 \text{ dBm}$   
 $F_s = 5 \text{ kHz}$   
 $T_{INT} = 0.1 \text{ sec}$   
 $N=500$   
Comp. = 10x

# Interleaved Radiometer Measurements

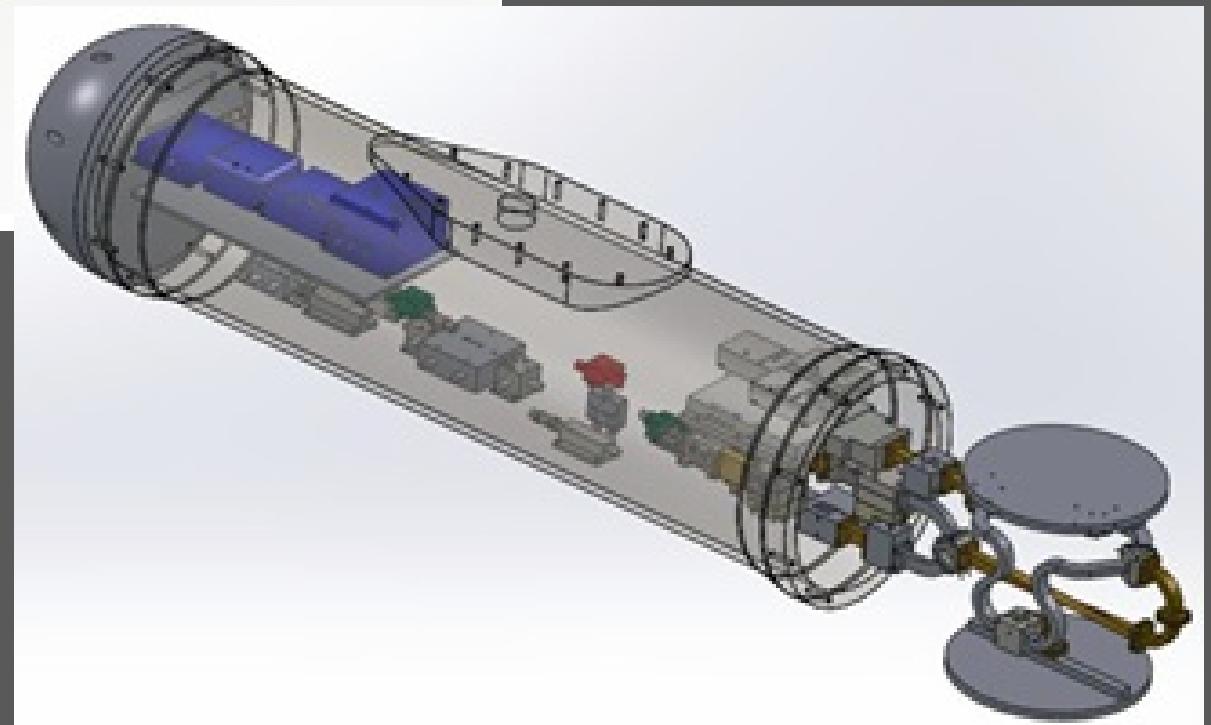
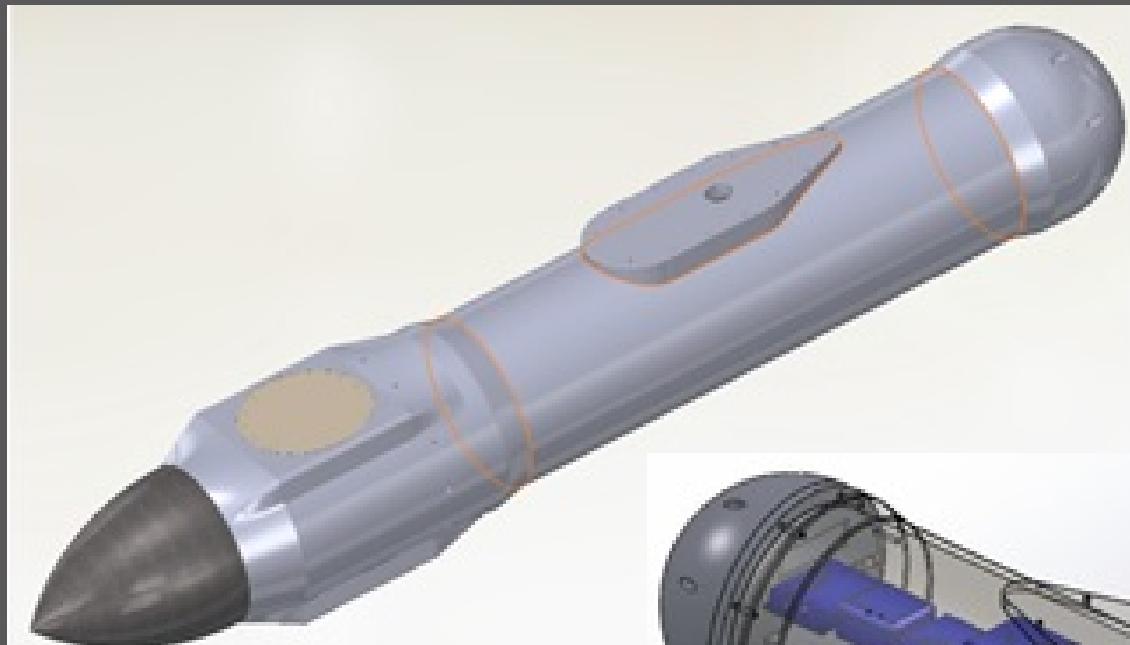
- LWP precision <  $\sim 0.02$  mm ( $< \sim 20$  g/m<sup>2</sup>)
- Requires a  $\Delta T_B < 0.5$  K
- $\Delta T_B = \frac{T_{ANT} + T_{SYS}}{\sqrt{B\tau}} \approx \frac{1000}{\sqrt{B\tau}}$
- $B\tau > 4e6$
- with Radar Data System:  
 $B = 40$  MHz, then  $\tau > 100$  ms
- with dedicated Radiometer Receiver:  
 $B = 200$  MHz, then  $\tau > 20$  ms

# Interleaved Radiometer Measurements

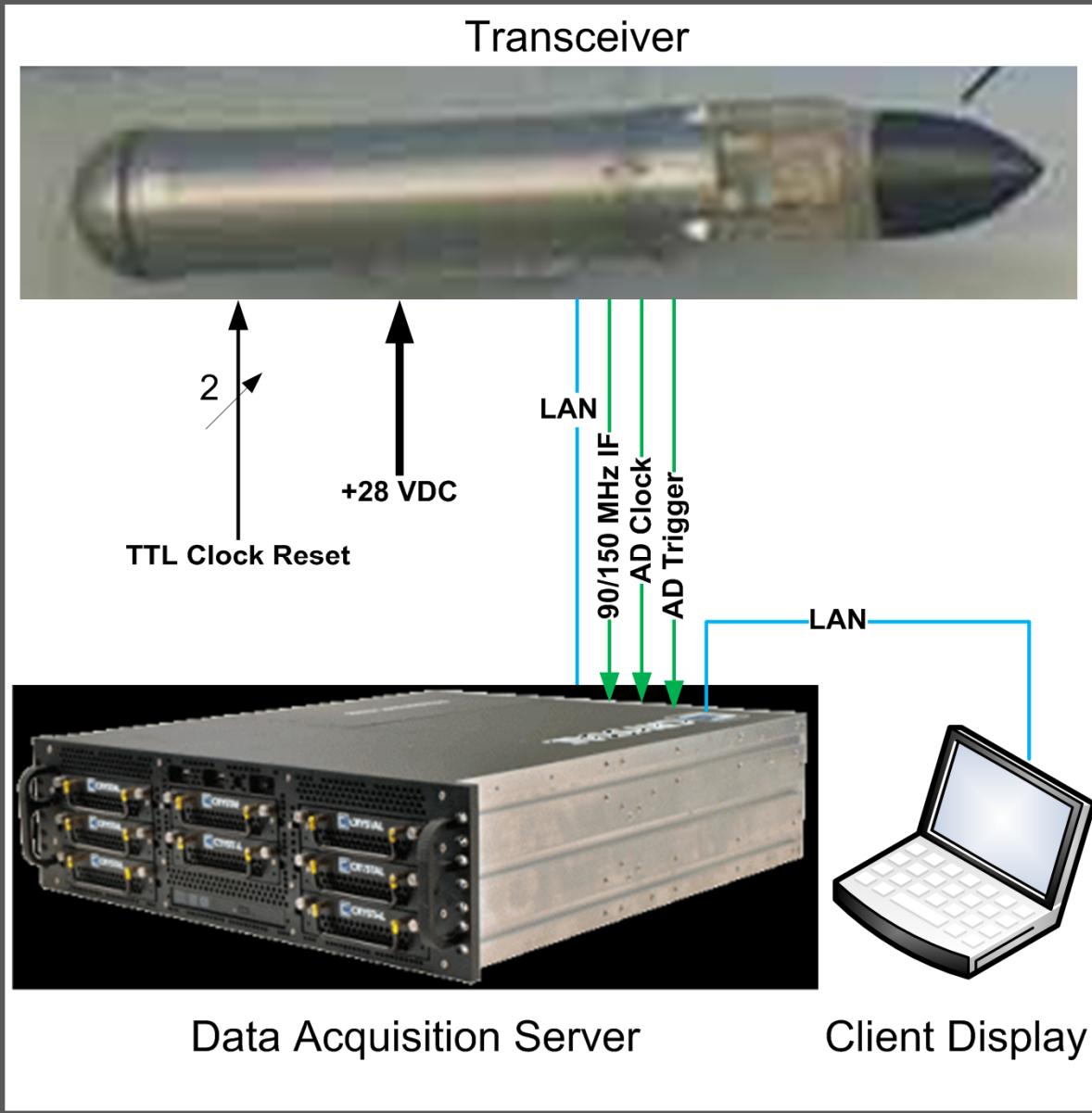
- 100 ms Integration-> 10-15 m Flight Distance
- 4.2° BW Antenna -> ~75 m footprint @ 1 km
- 150 ms radar period: 15-20 m flight distance
- 300 ms radiometer period: 30-45 m distance



# CAD Design



# System Diagram



The development of the first unit is being funded by NASA EPSCoR grant NNX13AN09A to the University of Wyoming.



# Interleaved Radiometer Measurements

- The observed brightness temperature can be estimated as

$$T_B = T_{BG} + (1 - L)T_{AT}$$

where

$$T_{BG} \approx 2.7 \text{ K}; T_{AT} \approx 280 \text{ K}$$

$$L = \exp(-0.23\alpha\Delta x) = \exp(-0.23\kappa LWP)$$

$\Delta x$  = attenuating distance in km

$\alpha$  = attenuation rate in dB/km

$\kappa$  = attenuation coefficient;  $\approx 0.6 \text{ dB km}^{-1} \text{ g}^{-1} \text{ m}^3$  liquid cloud at Ka-band

$m_V$  = liquid water content ( $\text{g m}^{-3}$ )

$LWP$  (Liquid Water Path in units of  $\text{g m}^{-2}$ ) =  $1000 m_V (\text{g m}^{-3}) * \Delta x (\text{km})$

$LWP$  (mm) =  $m_V (\text{g m}^{-3}) * \Delta x (\text{km})$

- $\Delta T_B \approx 0.13 \Delta LWP \times T_{AT} \exp(-0.13 \times LWP)$
- $\Delta T_B \approx 0.3 \text{ K}$ , if  $\Delta LWP = 0.01 \text{ mm}$  or  $10 \text{ g/m}^2$