

## ABSTRACT

Because phased array radar (PAR) technology It is assumed that the main beams of two-way patterns of all supports more flexible scanning strategies than radars subarrays encompass the same volume of space. using mechanically steered antennas (resulting in The cross-correlations between the subarray channels  $i_0$  and  $i_1$  in reduced data update times), this technology has been horizontal (h) as well as vertical (v) are computed as proposed as a foundation for the development of the next generation weather surveillance systems in the USA. Furthermore, the Spectrum Efficient National Surveillance Radar (SENSR) program is exploring the where c is h or v,  $V_c(m,i_0)$  as well as  $V_c(m,i_1)$  are subarray time feasibility of combining the functions of multiple series, and M is the number of samples in sample-time. The aircraft and weather surveillance radar national ensemble averages of cross-correlation arguments represent the networks into a single network of polarimetric phased phase differences induced by the system. array radar (PPAR) systems. While the use of PAR The ratios of returned powers from subarrays of the same technology for point target detection and tracking is polarization (h or v) are well established, the use of PPAR for polarimetric weather observations is still in the research stage and has been identified as particularly challenging. This is because weather measurements impose strict requirements on the beam shape matching of the copolar horizontal (H) and vertical (V) antenna where  $N_c(i_0)$  and  $N_c(i_1)$  are the noise powers in subarray channels. patterns, the levels of cross-polar patterns as well as By combining the measurements in (1) and (2), subarray the entire hardware in terms of signal purity and amplitude and phase (SAP) alignment is achieved. minimal cross coupling. Consequently, this significantly increases the PPAR calibration requirements. At the same time, many modern phased array radars are multi-channel systems which include multiple receiver channels for data acquisition. Each channel provides signal received from a group of T/R elements comprising a section of the antenna. Channels typically consists of a full receive path, often with an independent Local Oscillator Clock (LO) source. Such arrangement provides for beamforming flexibility on receive which can be applied in a digital domain. channel-to-channel phase Consequently, and amplitude alignment is critical to maximize the J Steering angle (deg) performance of the digital beamforming process and Fig. 1. Subarray phase difference before (left panels), and after (right panels) alignment. accuracy of the resulting detections and measurements. But due to the hardware imperfections \_P\_\_(3, 4) \_P<sub>sv</sub>(3, 4) – P<sub>sv</sub>(3, 5)  $-P_{sv}^{(3, 6)}$ and temperature variations, the time series produced -P<sub>sv</sub>(3, 7) – – P<sub>sv</sub>(3, 8) by the analog-to-digital converters (ADCs) in each channel intrinsically vary in amplitude and phase with respect to each other (thus, requiring alignment prior to J Steering angle (deg U Steering angle (deg Subarrays H polarizatioı ubarrays H polarizatio summation). Herein, an approach to improve channelto-channel alignment using weather signals from individual channels is described.

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## An Approach to Align Subarray Channels in PPAR Using Weather Returns

(1) Cooperative Institute for Mesoscale Meteorological Studies, The University of Oklahoma and NOAA/OAR National Severe Storms Laboratory, Norman, Oklahoma **Image: Contract of the second second** 

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## 2. THEORY

$$\hat{R}_{sc}(i_0,i_1) = \frac{1}{M} \sum_{m=0}^{M-1} V_c(m,i_0) V_c^*(m,i_1)$$
(1)

$$\hat{P}_{sc}\left(\vec{r},i_{0},i_{1}\right) = \frac{\frac{1}{M}\sum_{m=0}^{M-1}\left|V_{c}\left(\vec{r},m,i_{0}\right)\right|^{2} - N_{c}\left(i_{0}\right)}{\frac{1}{M}\sum_{m=0}^{M-1}\left|V_{c}\left(\vec{r},m,i_{1}\right)\right|^{2} - N_{c}\left(i_{1}\right)}$$
(2)







Fig. 2. Subarray power ratio before (left panels), and after (right panels) alignment.





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coefficient without (c), and with SAP (d). Differential phase without (e), and with SAP (f)

![](_page_0_Figure_24.jpeg)

correlation coefficient.

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