# Sensitivity analysis in linear and nonlinear models: A review 

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## Introduction

Consider:


Question: How do the inputs affect the outputs?
General Answer: Sensitivity Analysis (SA).
However, different people mean different things by SA. E.g.

- How does input uncertainty propagate (Uncertainty A.)?
- How does the addition of a new observation affect the outcome?
- How is output uncertainty apportioned among the inputs?

And they do it for different reasons. E.g.

- Knowledge discovery.
- Ranking of the inputs.
- Dimensionality Reduction.
- Model tuning. Etc.


## Introduction ...

Three components:

1) Experimental Design.

- Make or break.
- No experimental error. Computer Data. In vitro vs. In silico.
- How should the inputs be selected?
- To optimize accuracy and precision.
- random sampling will not give the most precise estimate.

2) Choice of SA method.

- Performance vs. inclusion/exclusion of inputs.
- One At a Time.
- High-dimensional space is mostly corners.
- Generally three types:
- Local (derivatives, adjoint),
- Screening (factorial designs)
- Global (variance-decomposition)

3) Method for estimating conditional expectations.

- Monte Carlo
- Emulation (Gauss Process/Krig, Poly. Regression, NN, ...)

A few issues specific to computer experiments:

- No experimental error to minimize.
- Emulator must have zero error on training set.
- Error on test set must be consistent with realistic uncertainty.

Q: Why $\mathrm{AI} / \mathrm{CI}$ ? $\quad \mathrm{A}: 1$ and 3 .

## Experimental Design

Q: What values of the inputs should be selected?

- Impossible to explore all values. So, sample!
- Simple random sample does not give most precise estimates.
. - Who cares?


With low precision (black): Cannot pick better algorithm. If/when forced, may take B.
But with higher precision, A wins.

- Space-filling samples/designs give more precise estimates. E.g.,
- Latin hypercube sampling


A simple random sample (black) and a latin square sample (red). No 2 red dots have a row or col in common.

## Simple random vs. Latin square sampling

Estimate mean of z-axis:


Distribution of means according to simple random (black) and latin square (red) sampling, for different sample sizes. True mean $=$ horizontal line .

## Variance-Based SA

Two "theorems" save the day:

$$
\begin{gathered}
\operatorname{Var}[Y]=E[\operatorname{Var}[Y \mid X]]+\operatorname{Var}[E[Y \mid X]] \\
Y=\eta\left(X_{1}, X_{2}, \ldots\right)=E[Y]+z_{1}\left(x_{1}\right)+z_{2}\left(x_{2}\right)+z_{12}\left(x_{1}, x_{2}\right)+\ldots
\end{gathered}
$$

where

$$
\begin{gathered}
z_{i}\left(x_{i}\right)=E\left[Y \mid x_{i}\right]-E[Y] \\
z_{12}\left(x_{1}, x_{2}\right)=E\left[Y \mid x_{1}, x_{2}\right]-E\left[Y \mid x_{1}\right]-E\left[Y \mid x_{2}\right]+E[Y]
\end{gathered}
$$

## Measures of Sensitivity

Reduction in uncertainty of $Y$, after $X_{i}$ is learned:

$$
V_{i}=\operatorname{Var}\left[E\left[Y \mid X_{i}\right]\right]
$$

Reduction in uncertainty of $Y$, after $X_{1}$ and $X_{2}$ are learned:

$$
V_{12}=\operatorname{Var}\left[E\left[Y \mid X_{1}, X_{2}\right]\right]
$$

Uncertainty in $Y$ remaining, after $X_{2}$ is learned:

$$
V_{T 1}=\operatorname{Var}[Y]-\operatorname{Var}\left[E\left[Y \mid X_{2}\right]\right] \quad(1,2) \text { not a typo! }
$$

Main effect index of $X_{i}$ :

$$
S_{i}=V_{i} / \operatorname{Var}[Y]
$$

Total effect index of $X_{i}$ :

$$
S_{T i}=V_{T i} / \operatorname{Var}[Y]
$$

Example 1

$$
Y=\eta\left(X_{1}, X_{2}\right)=X_{1}
$$

|  | General | Indep $X_{1}, X_{2}$ |
| :---: | :---: | :---: |
| $z_{1}$ | $x_{1}-E\left[X_{1}\right]$ | $x_{1}-E\left[X_{1}\right]$ |
| $z_{2}$ | $E\left[X 1 \mid X_{2}\right]-E\left[X_{1}\right]$ | 0 |
| $z_{12}$ | $-z_{2}\left(x_{2}\right)$ | 0 |
|  |  |  |
| $V_{1}$ | $V\left[X_{1}\right]$ | $V\left[X_{1}\right]$ |
| $V_{2}$ | $V\left[E\left[X_{1} \mid X_{2}\right]\right]$ | 0 |
| $V_{12}$ | $V\left[X_{1}\right]$ | 0 |
| $V_{T 1}$ | $V\left[X_{1}\right]-V_{2}$ | $V\left[X_{1}\right]$ |
| $V_{T 2}$ | 0 | 0 |
| $S_{1}$ | 1 | 1 |
| $S_{2}$ | $V_{2} / V\left[X_{1}\right]$ | 0 |
|  |  |  |
| $S_{T 1}$ | $1-S_{2}$ | 1 |
| $S_{T 2}$ | 0 | 0 |

## Example 2

$$
Y=\alpha+\beta_{1} X_{1}+\beta_{2} X_{2}+\beta_{12} X_{1} X_{2}
$$

Theorem: Things are messy. Proof:

$$
\begin{aligned}
z_{1} & =\beta_{1}\left(x_{1}-E\left[X_{1}\right]\right) \\
& +\beta_{2}\left(E\left[X_{2} \mid X_{1}\right]-E\left[X_{2}\right]\right) \\
& +\beta_{12}\left(x_{1} E\left[X_{2} \mid X_{1}\right]-E\left[X_{1} X_{2}\right]\right) \\
z_{2} & =\text { similar } \\
z_{12} & =\beta_{1}\left(E\left[X_{1}\right]-E\left[X_{1} \mid X_{2}\right]\right) \\
& +\beta_{2}\left(E\left[X_{2}\right]-E\left[X_{2} \mid X_{1}\right]\right) \\
& +\beta_{12}\left(x_{1} x_{2}-x_{1} E\left[X_{2} \mid X_{1}\right]-x_{2} E\left[X_{1} \mid X_{2}\right]-E\left[X_{1} X_{2}\right]\right)
\end{aligned}
$$

Even for indep. $X_{1}, X_{2}$, and $E\left[X_{i}\right]=0$

$$
\begin{aligned}
z_{1} & =\beta_{1} x_{1}-\beta_{12} E\left[X_{1} X_{2}\right] \\
z_{2} & =\beta_{2} x_{2}-\beta_{12} E\left[X_{1} X_{2}\right] \\
z_{12} & =\beta_{12}\left(x_{1} x_{2}-E\left[X_{1} X_{2}\right]\right)
\end{aligned}
$$

Etc. for $V_{i}, V_{T i}, S_{i}, S_{T i}$.
Moral:
If model $=$ linear $\left(\beta_{12}=0\right)$, the $S_{i} \sim(\text { std regress coeff })^{2}$.
Else, not, and complicated.

## Example 3

Black Box = Lorenz, 1963


Inputs $=s, r, b$.
Outputs $=X_{\max }, Y_{\max }, Z_{\max }$.


## Main conclusion for Lorenz

All sensitivity measures:


According to most measures, $X_{\max }$ is

- most sensitive to $r$,
- not so sensitive to $s$, and $b$,
- but there exists an "interaction" between $s$ and $r$,
- and between $r$ and $b$,
- but not as much between $s$ and $b$.

Peeking into the black box
The blackbox according to one NN emulator:


## Final Remarks

- Sensitivity Analysis is intuitive, but ambiguous.
- Careful attention to experimental design is crucial.
- Variance-based methods naturally tie SA to emulators.
- Not clear (to me) if "fancy" emulators are necessary.
- Many AI techniques come with natural ranking of inputs.
- But in most, an "explanation" is lacking.
- Ranking based on variance is explanatory.
- But does not assure better performance.

Coming soon:

- Emulation with gaussian process (zero trn error) vs. NN (not).
- Extension to Multivariate (multiple output).
- Orthogonal designs to address collinearity.
- Connection with ensemble methods.


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