

Assessment of S-NPP CrIS Radiometric and Spectral Accuracy using Community Radiative Transfer Model

Yong Chen^{1,2}, Yong Han³, and Fuzhong Weng³

Contact info: Yong.Chen@noaa.gov

¹CIRA, Colorado State University, Fort Collins, CO 80523 ²Joint Center for Satellite Data Assimilation, College Park, MD 20740

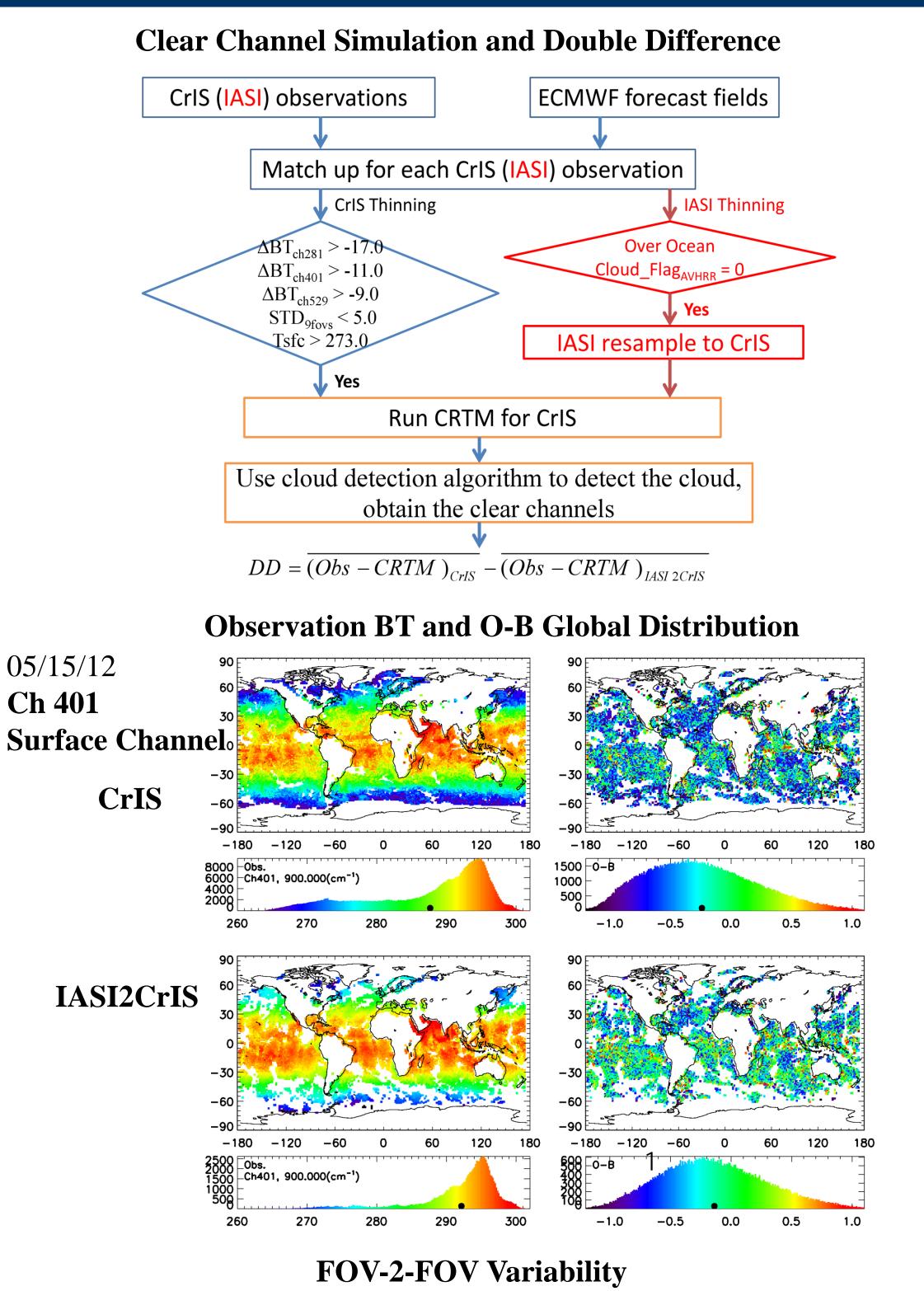
2013 AMS Poster No. 676

³NOAA/NESDIS Center for Satellite Applications and Research, College Park, MD 20740

Abstract

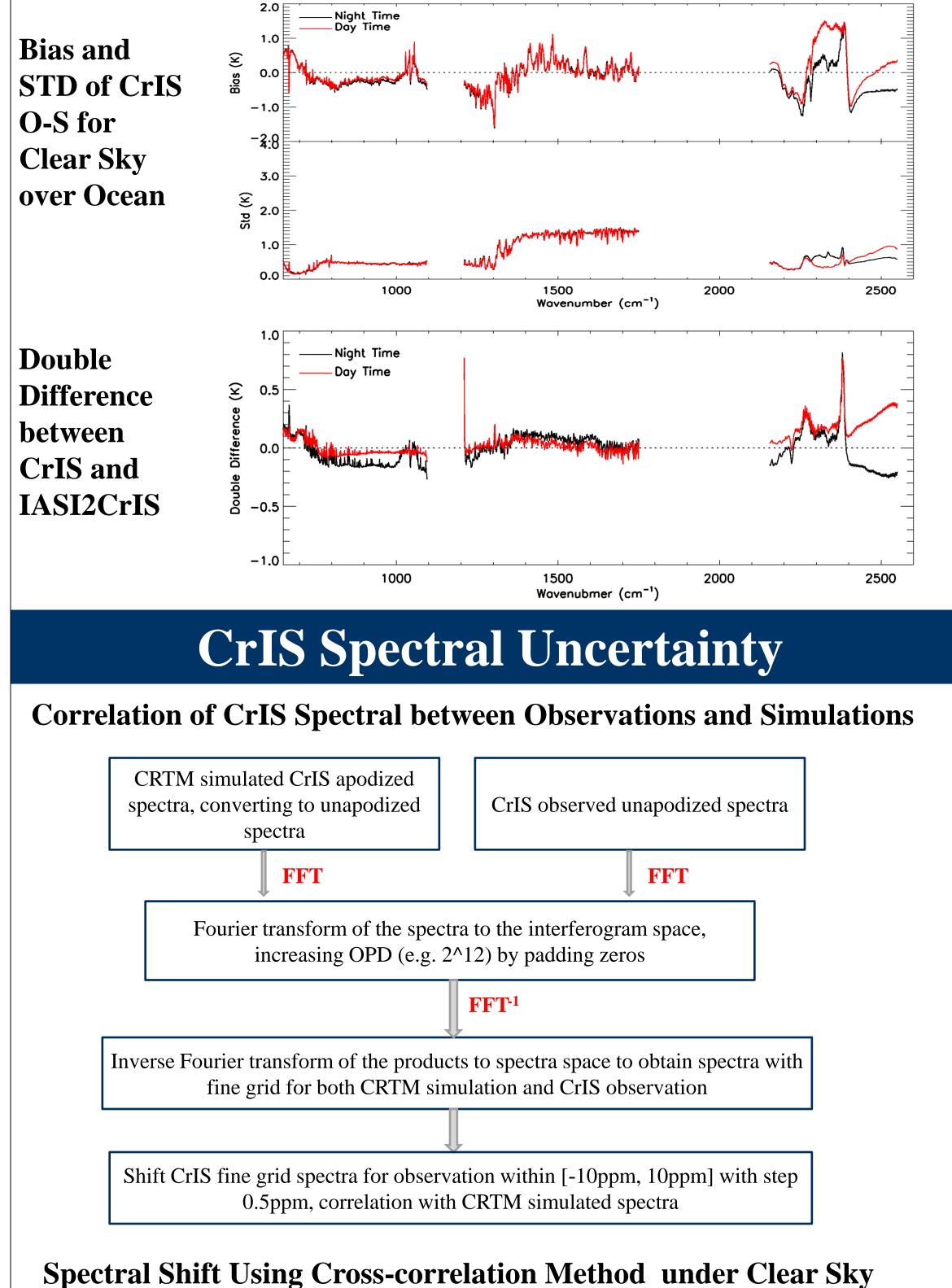
The Cross-track infrared Sounder (CrIS) on Suomi National Polar-orbiting Partnership Satellite (S-NPP), is a very important Fourier transform interferometer and provides soundings of the atmosphere with 1305 channels. The sounding information will be used to enhance weather forecast help improve understanding of climate change. and Quantifying the CrIS radiometric and spectral accuracy, and bias with other hyper-spectral infrared sensors such as Infrared Atmospheric Sounding Interferometer (IASI) on MetOp are crucial for creating fundamental climate data records and intercalibrating other infrared sensors. The CrIS Sensor Data Record (SDR) data sets were assessed by using Community Radiative Transfer Model (CRTM) and ECMWF forecast data for clear sky and over ocean and compared with IASI data. The CRIS SDR data sets were evaluated to estimate the FOV-2-FOV variability and sweep direction bias. Results show that FOV-2-FOV variability is small; The sweep direction bias among FORs is also small. Results from the double difference with IASI show that the differences are within ± 0.2 K for most of channels. The CrIS spectral accuracy is also assessed by using the cross-correlation method to compare the CrIS fine grid spectral between observations and CRTM simulations. About 3 ppm and 4 ppm uncertainty are found in CrIS SDR data in band 1 (LWIR), and band 2 (MWIR), respectively. Overall, CrIS SDR meets the high quality standard for the usage by NWP and the scientific community.

CrIS Radiometric Accuracy



(remove the mean bias between observations and CRTM simulations)

 $BIAS_{FOV_i} = (Obs - CRTM)_{FOV_i} - (Obs - CRTM)_{all}$

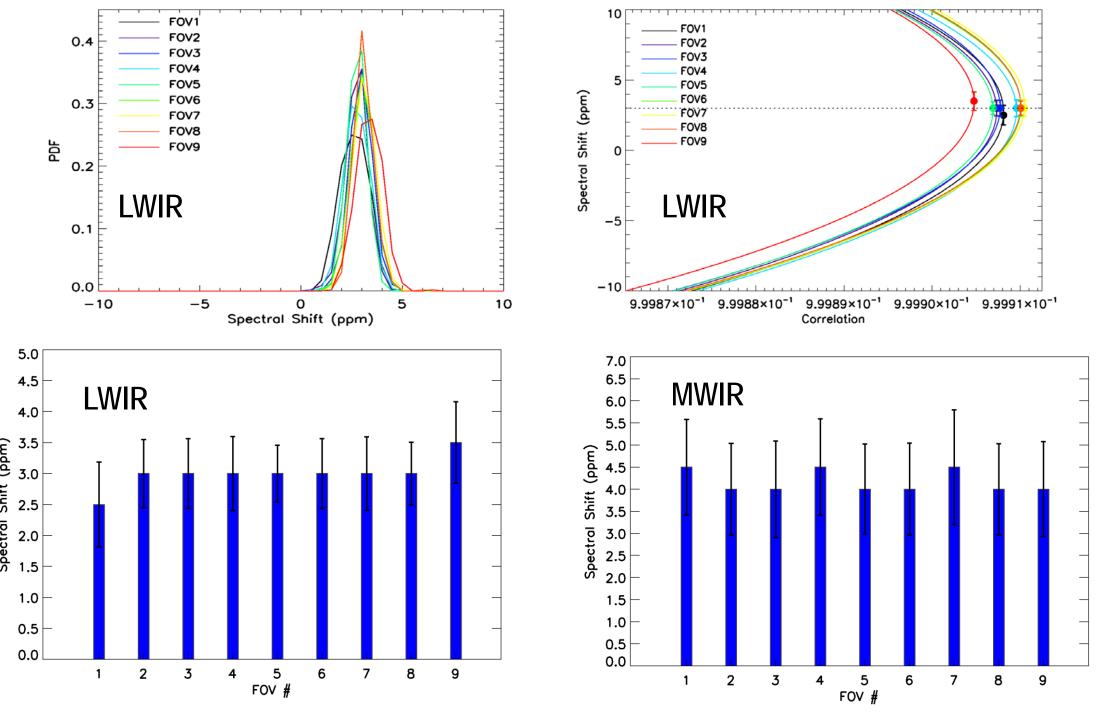


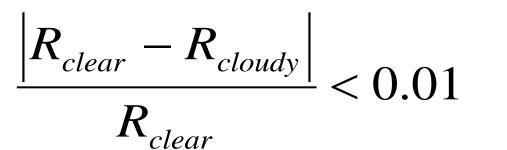


IR Cloud Detection Algorithm

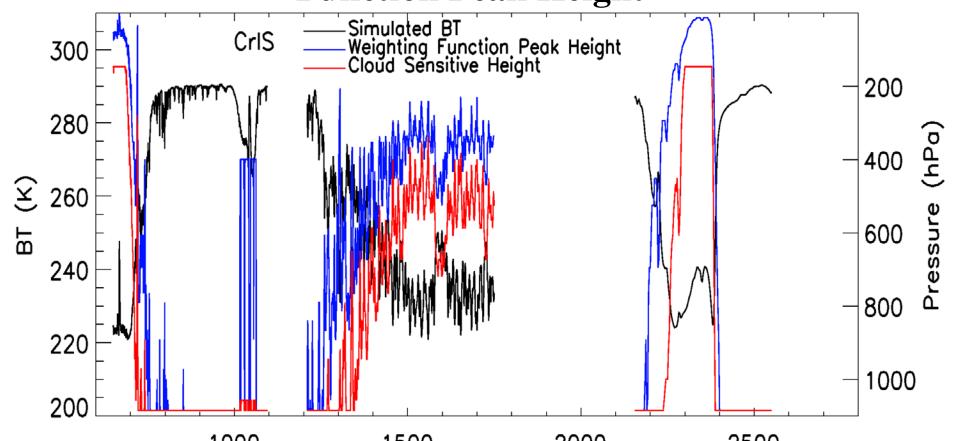
The channels are first ordered according to their cloud sensitivity (with the highest channels first and the channels closest to the surface last) (McNally and Watts, 2003) overcast variable contains overcast radiances assuming the presence of a black cloud at each of CRTM levels. The height for a particular channel is assigned by finding the level where the difference between the overcast and clear radiances is less than 1%.

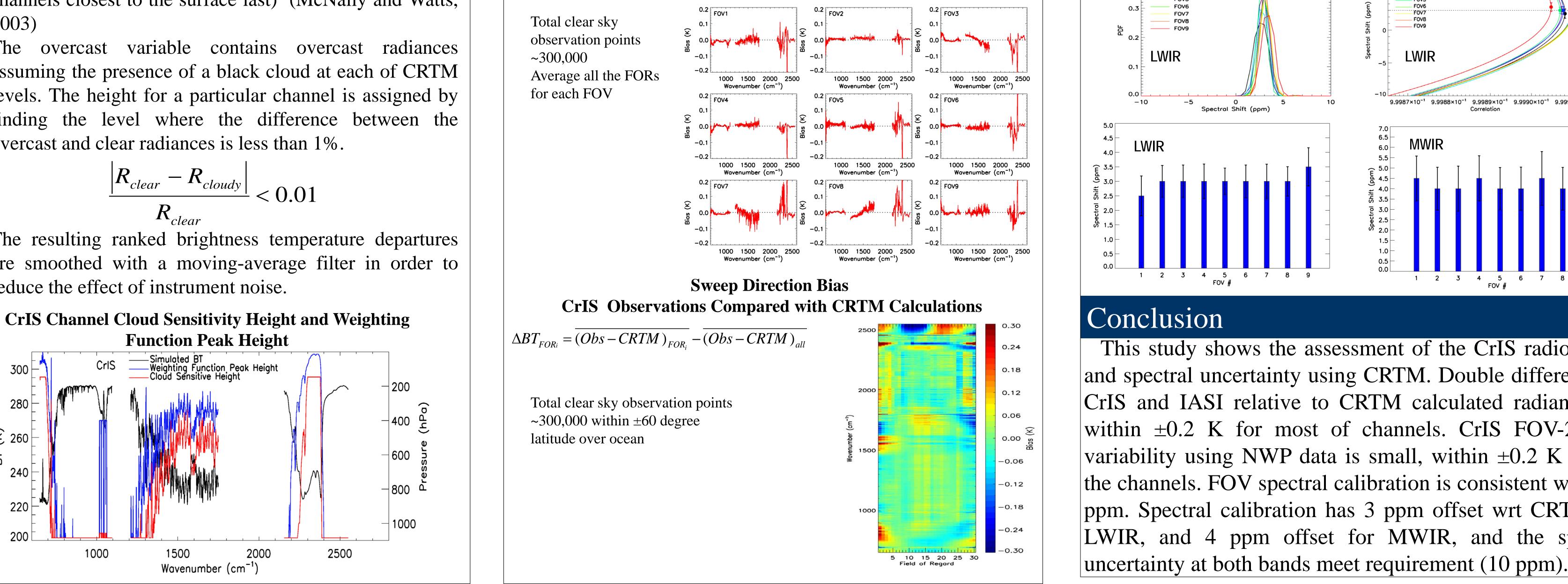






The resulting ranked brightness temperature departures are smoothed with a moving-average filter in order to reduce the effect of instrument noise.





This study shows the assessment of the CrIS radiometric and spectral uncertainty using CRTM. Double difference of CrIS and IASI relative to CRTM calculated radiance are within ±0.2 K for most of channels. CrIS FOV-2-FOV variability using NWP data is small, within ± 0.2 K for all the channels. FOV spectral calibration is consistent within 1 ppm. Spectral calibration has 3 ppm offset wrt CRTM for LWIR, and 4 ppm offset for MWIR, and the spectral