## The Effects of Numerical Noise on Perturbation Experiments

### **INTRODUCTION**

Perturbation experiments are useful for applications such as data assimilation observation impact experiments, simulations to investigate inadvertent weather modification, or forecast sensitivity runs. In turn, numerous studies have executed perturbation experiments, measuring key differences between simulations that differ by their initial conditions. It has been discovered, however, that perturbations can introduce noise to model variables not physically related to the perturbation, which can grow rapidly through nonlinear processes. This work aims to understand whether these effects can lead to misinterpretations of perturbation experimental results.



### **BACKGROUND AND MOTIVATION**

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 $\rightarrow$  Growth rates within moist convection are much more rapid for the smallest perturbations

• These nonlinear growth processes provide the mechanism for very small perturbations to significantly affect forecasts

OKM	500KM	1000KM	1500KM	2000KM
0	0	0	0	0
-0.179	2.5x10 <sup>-5</sup>	0	0	0
-0.288	4.7x10 <sup>-5</sup>	2.4x10 <sup>-7</sup>	0	0
-0.06	4.8x10 <sup>-5</sup>	-6.8x10 <sup>-5</sup>	5.0x10 <sup>-6</sup>	0
-0.07	-6.1x10 <sup>-5</sup>	1.3x10 <sup>-5</sup>	5.5x10 <sup>-5</sup>	-1.2x10 <sup>-5</sup>

Horizontal propagation of numerical noise to the surface potential temperature field (K) relative to the source of the perturbation

# within perturbation experiments?







- Rapid propagation and growth of numerical noise within convection is an efficient mechanism through which chaos can amplify unrealistic effects - Such "contamination" can indeed contribute to misinterpretations of perturbation experimental results such as those involved with data assimilation impact or forecast sensitivity experiments

# METHODOLOGY -Perturbation experiments are executed using the WRF-ARW

mesoscale model V3.5.1 with nonlocal soil moisture perturbations to the initial conditions - Perturbation effects are examined for nonlocal convection

Precipitation differences begin 2-3 hr after initialization, and are very likely the result of rapid growth of fastspreading numerical noise



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### IMPLICATIONS

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