

EVEREST: AN INTEGRATED WEATHER PRODUCTS TESTBED FOR NORTHROP GRUMMAN **ENVIRONMENTAL REMOTE SENSING SATELLITE SYSTEMS**

Introduction **Environmental Scene Requirements for Test Data** Complete view the scene Realistic - Geophysical parameter values for a given scene should be those that occur in nature - All natural correlations that exist between the various geophysical parameters should be contained in the scene data Representative viewed by sensors on the spacecraft Comprehensive - A significant range of all naturally occurring scenes, both typical and extreme, must be adequately sampled in the test data - There must be a sufficient number of samples to assess EDR performance over all required stratifications Realistic Complete Atmospheric Profiles of Temperature **High-Resolution 3D Cloud Simulation** What Does EVEREST Do? oisture and Ozone Constructed from **EVEREST Block Diagram** CEP GDAS or MM5. CIRA-86 & UARS Temperature Profiles should be contained in "realistic" data Sensor Radiometric Image/Data Sensor Sensor/Space-**Mission/Orbit** diance arriving at sensor along redicted Geophysica Variables craft Factors Variables ale or multiple lines-of-sight Properties of 3D Scene correlations is "estimate" of this radiance after **High-Resolution Terrain Simulation** moving known sensor biases Sensor SDR data, as well as 200 220 240 260 280 300 Water Vapor Profiles 2.5 ^x 10 uxiliary and ancillary data. Environmenta re used in statistical = -0.12K Mn Scenes: Sdev = 1.63K<u>ometric Elements of a 3-D Scer</u> Atmospheric nospheric attenuation, emission, eophysical properties of Conditions Radiative Simulated Spacecraft **Simulated Sensor** ivironmental scene bein tinction and dispersion by water/ice Background Conditions Transfer Radiances a **Sensor Models** 10⁻² 10⁻¹ 10⁰ Ozone Profiles ewed Measurements ouds, aerosols and rain Aperture **INR Processing** Models errain/ocean scattering and emissior ŏ 0.5 **APU Performance** Environmental **Evaluate End** Comparison of Predicted Metrics **Products** Physical Elements of a 3-D Scene to-End Geophysical Properties Performance Retrieval 10 -10 -5 -10 1000 1500 Algorithm with Scene <u>"Truth"</u> zone, aerosols, haze/fog/cloud Air/Land Temperature Difference (K) Global dataset based on 12 days of NCEP analyses (1 day/month) Compute resulting in over 3 million atmosphere/surface situations Statistics 0 272 274 276 278 280 282 284 SST Truth (K) Physics-based phenomenology and sensor/spacecraft models to verify data products performance within required precision, accuracy and uncertainty Representative **Sampling Based on NPOESS Orbits 4D Distribution of Atmosphere** NCEP GDAS & Required: 180-335 K _ x 10⁴ Sampled: 181-322 K And Surface Conditions & Sensor Geometry **Climatology Data Algorithm Timing & Dependency** Tropopause Near Surface **Simulation Predicts System Latency Models & Datasets** Geophysical Scene Databases & Models Scene Generation and Radiative Transfer **ATDS Model** REL. HUMIDITY (%) @850mb Models Latency from Sensor Data 250 Land Cover & Digital Elevation Databases Models Temperature (K) Collection to Product Generation Space & Sensor Model NGST Enhanced PSU/NCAR Mesoscale MODTRAN 4v3R1 (uses functional and **Data Collection** Required: 271-313 K 1330 , 1730 , Model Package tabular BRDFs) Space and Sensor Modeling _ x 10⁴ Sampled: 270-315 K **1D Geophysical Properties at** istribution of atmosphere/surface conditions in space NWP Databases & models for atmosphere Custom fast transmittance infrared radiative - Configurable satellites and sensors **Sampled Locations & Times** & time is provided by NCEP & climatology and surface conditions transfer model NPP 🚽 <u>SST</u> Dynamic data collection & retrieval from NGST/NGIT Cloud Scene Simulation Model SOS – Vector RTM **Ground Product** ampling of global positions, times and solar/sensor NPOESS orbits Real or Proxy Data (Hyperion, SeaWiFS, Hydrolight 4.0/HydroMod II for CW/OO RT **NCEP Weather** viewing angles is obtained by "flying" sensor for Ground Product Generation MODIS, AIRS/AMSU/HSB) DISCORD BRDF model for snow/ice RT IPOESS 1330 and 1730 orbits Models algorithm data dependencies wiring diagrams oduces ~540.000 atmosphere/surface conditions **Orbit and Spacecraft Effects** Models algorithm sensitivity to scene presentative of what the sensor should observe on Scene Example Orbit and geolocation model 290 300 weather, terrain & day/night 280 310 User-specified line of sight jitter power Ops. Algorithms Temperature (K) Data Processing Architecture spectral density Ocean - Supports architectural & Clouds **Full Resolution Sensor Sampling** cost/latency/quality trades Vis/IR Sensor Models – Uses orbital & weather dynamics to size^L Vis/IR Imager (customized for various) NGST Sounder retrieval & heritage algorithms Copyright 2007 NGC Inc. All rights reserved. algorithm processing **For Structured Scenes** sensors) MODIS algorithms CW/OO Imager Optics Trades Analyzer NPOESS/NPP algorithms **NOAA88B Test Dataset** FTS Sounder SNR Model **ATDS Models Data Latency from Sensors to Product Generation Cloud Top Heights** Dispersion/filter-based multi/hyperspectral for Systems like NPOESS & GOES-R The ^D Cloud Layers SNR Model **Precipitable Water** The Mar -Surface **Radiative Transfer Models Sensor Models** Ch Temperature Status of EVEREST RTMs Radiative Frequency Frequency Model Name **EVEREST** Capability Transfer Model Regime Regime Detailed Vis/IR sensor model Vis/IR MODTRAN-4 MODTRAN, 5S(V), and UCLA's LBLRTM are community Total of 7,547 samples clustered standard atmospheric RTMs with known fidelity and limitations around specific geographic LBL-RTM Validated against other VIS/IR models **VIRRISM*** Vis/IR • Modifications to MODTRAN and 6S(V) allow input of locations 6S & 6SV • Includes effects of optical aberrations and line-of-sight jitter ocean/terrain BRDF tables Only 1,270 samples for open ocean HydroLight • Currently used to model VIIRS, HES CWI and ABI • HydroLight BRDF (H-BRDF) ocean RTM, and DISCORD & **Environmental Properties Displayed** BRDF Insufficient samples for stratified • Fourier Transform Spectrometer (FTS) radiometric model ISBRDF snow/ice RTMs generate BRDF tables read by at Vis/IR sensor Pixel Locations testing of EDR retrieval algorithms DISCORD MODTRAN & 6S(V) to provide coupled ocean-atmosphere • Developed 1st principles model; initial comparison with other and snow/ice-atmosphere RTM capabilities ISBRDF model gives good results IR Sounder NGSTFTS Includes effects of optical aberrations and line-of-sight jitter • High spectral resolution atmospheric RTM for modeling NGST-ARMSS hyperspectral IR sounders Summary • Used to model GIFTS and HES DS • NGST's ARMSS model for microwave RTMs (see below) Developed generic m-wave sensor model (used to model) AMSU-A and AMSU-B) can also be used as back-up for ATMS UV MODTRAN-4+ • Community standard, useful for: TC, NP & LP products generated by sensors onboard polar and geo-synchronous orbiting satellites, as well as airborne platforms • Developed generic m-wave sensor model used to model Microwave/ HERMAN HERMAN used in Limb Profile retrieval software [Not a flat AMSU-A and B, and test performance of SSM/I and AMSR on Millimeterearth & horizontal inhomogeneity to be implemented into ARMSS EVEREST remote sensing capability spans the EM spectrum - from Ultra-violet to Microwave **EVEREST** EVEREST scene generation] wave Model

An essential tool for an environmental remote sensing mission developer or system integrator is the ability to predict the impact various elements of the system on the performance of the environmental data products (EDR) delivered by the system. EVEREST is an end-to-end modeling and simulation testbed developed by Northrop Grumman to support the NPOESS program, as well as other similar programs, in assessing the performance of EDR during the various phases of the program. It supports design trades early in the development phase, verification testing of sensor data and weather retrieval algorithms, independent performance assessment of impact of sensors developed on EDR, and support of on-orbit calibration and validation of the data products. The testbed is comprised of five main components: global environmental databases covering typical and extreme environmental conditions, radiative transfer models covering the microwave, optical, and ultra-violet frequency regimes, detailed sensor models capable of reproducing the effects observed by the actual sensors being build, spacecraft models for pointing and jitter, and retrieval algorithms to calculate the weather data records. In addition, EVEREST is also comprised of a detailed event-based simulation that computes latency and processing load for the system. The presentation will highlight the main features of the testbed and how it is used to assess performance of the data products.



Millimeter-

wave

• Components verified with published results for other μW Microwave/ NGST-ARMSS⁺ models

Sounding &

Grumman Corp.)

Imaging

• End-to-end RT compared with field experiments on previous NGST programs • Sanity check with simulated SSM/I and AMSU data • Ongoing validation effort using SSM/I, TMI, AMSR-E and

WindSat data

Bruce Hauss and Merit Shoucri

Northrop Grumman Space Technology, Redondo Beach, California, 90278

• Used to produce millimeter wave imaging scene and signature *VIRRISM – Visual/Infrared Radiometric Imaging Sensor Model (Copyright - Northrop Grumman Corp.) + ARMSS – Advanced Radiometric Microwave/Millimeter-wave Scene Simulation (Copyright – Northrop

• EVEREST leverages recognized capabilities in the larger community as well as a dedicated team trained to be both scientists and engineers

