

Figure 3. Two channel digital receiver/signal processor, accepting IF frequencies from 0 to 28 MHz. The FPGA processor performs up to 14,000 512 point FFTs per second to generate range profiles of the complex voltage. The voltage profiles are further processed by the FPGA into velocity and reflectivity profiles.

The radar's minimum detectable sensitivity, predicted from the radar range equation [1], is plotted in Figure 5, for 30 m range resolution. The range resolution is continuously variable from 5-300 m, which is governed by the bandwidth of the digitally synthesized chirp waveform. The radar has a minimum range of approximately 20 m, where it achieves better than -45 dBZ sensitivity at 5 m range resolution.

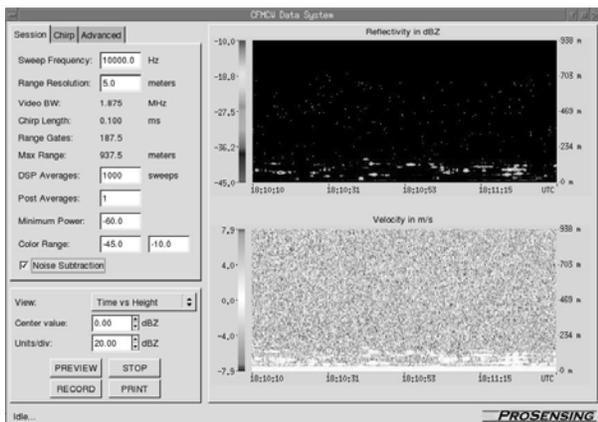


Figure 4. Graphical user interface for radar control and display of data products. Time/height plots of reflectivity and velocity for insects gathered April, 2002 in Amherst, MA are shown with the system configured for 5 m height resolution, 10 kHz PRF, and 0.1 s averages.

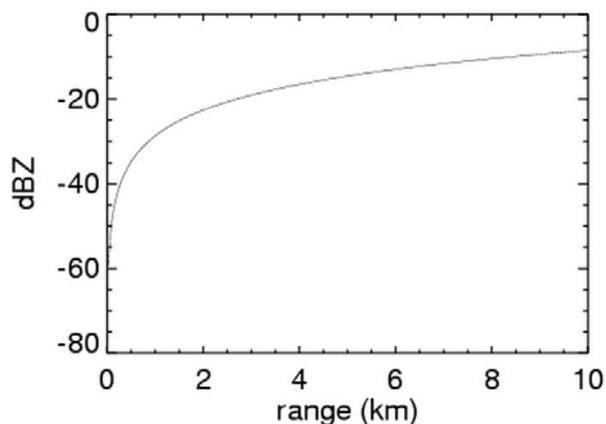


Figure 4. Minimum detectable reflectivity assuming 30 m range resolution, .25 second averaging, 2 kHz PRF, and 2 percent false detection rate.

An example reflectivity image for an ice cloud measured during December 2002 from the roof of ProSensing's facility in Amherst, MA is shown in Figure 6. More data gathered during the winter of 2002/2003 can be downloaded from the ProSensing web site, www.prosensing.com.

The radar is currently operated by the Rosenstiel School of Marine and Atmospheric Science, University of Miami, with airborne experiments planned for the summer of 2003, based out of the CIRPAS facility in Marina, CA.

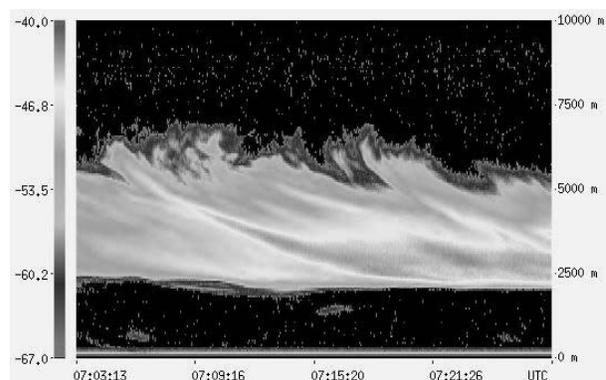


Figure 5. Time/height plot of backscattered power (uncalibrated reflectivity) for an ice cloud passing over Amherst, MA, December 25, 2002.

[1] Lhermitte, R. *Centimeter and Millimeter Wavelength Radars in Meteorology*, Lhermitte Publications, 2002, ISBN-0-9719372-0-6, pg. 248.